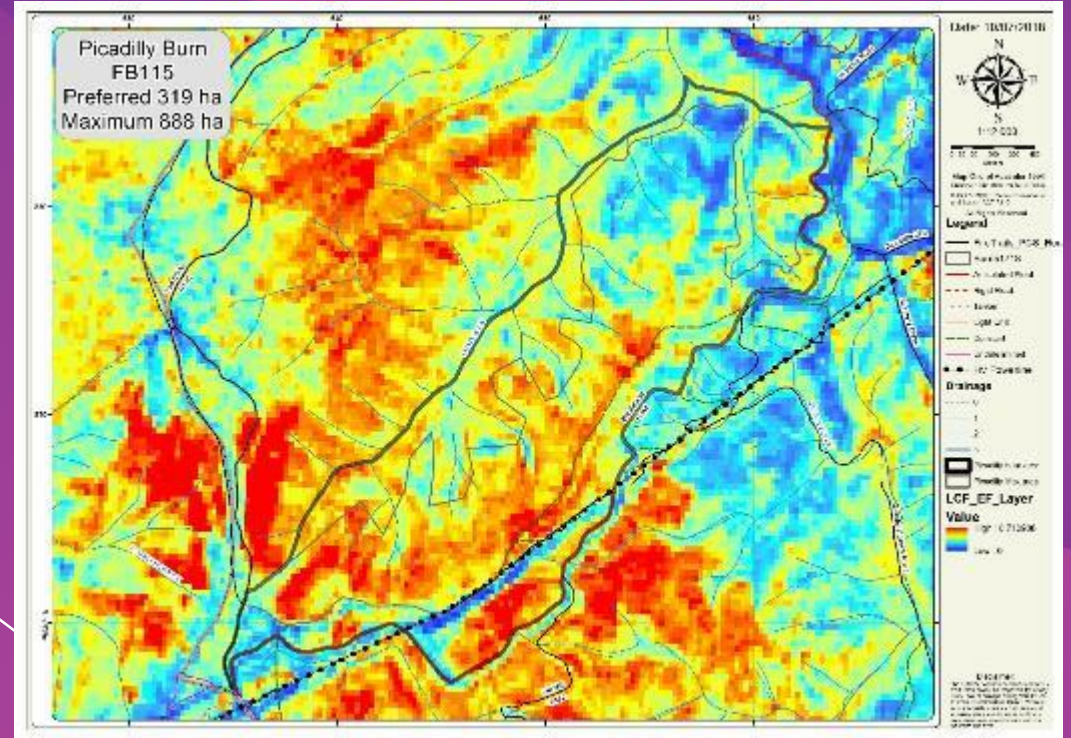


ACT GOVERNMENT

A LiDAR-derived Fuel Map for the ACT

Adam Leavesley, Albert Van Dijk and Marta Yebra





I'M GOING TO TALK ABOUT:

1. Value of LiDAR
2. ACT acquisition
3. Contractor processing
4. Experimental processing
5. Qualitative truthing
6. Next steps



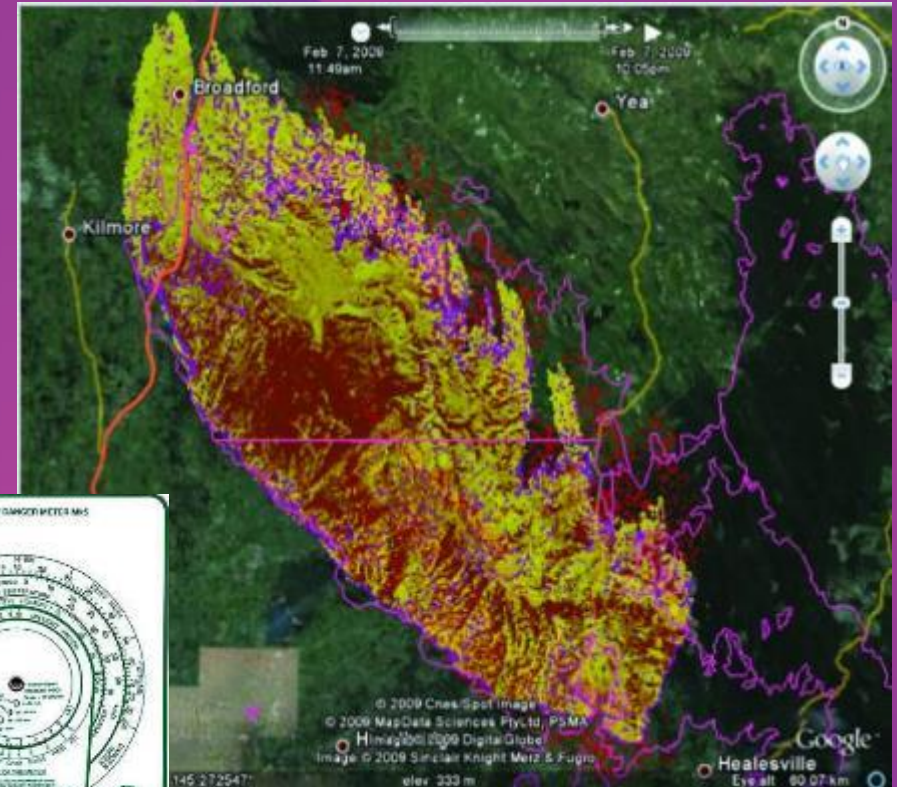
Why invest in LiDAR for fuel mapping?

1. Inadequate knowledge of fuels and fuel condition was implicated in the Margaret River (Keelty, 2012) and Lancefield escapes (Carter *et al.* 2015).



Why invest in LiDAR for fuel mapping?

2. Spatially-explicit knowledge of the variation in the distribution of fuels may reduce some of the unpredictability of wildfire behaviour.

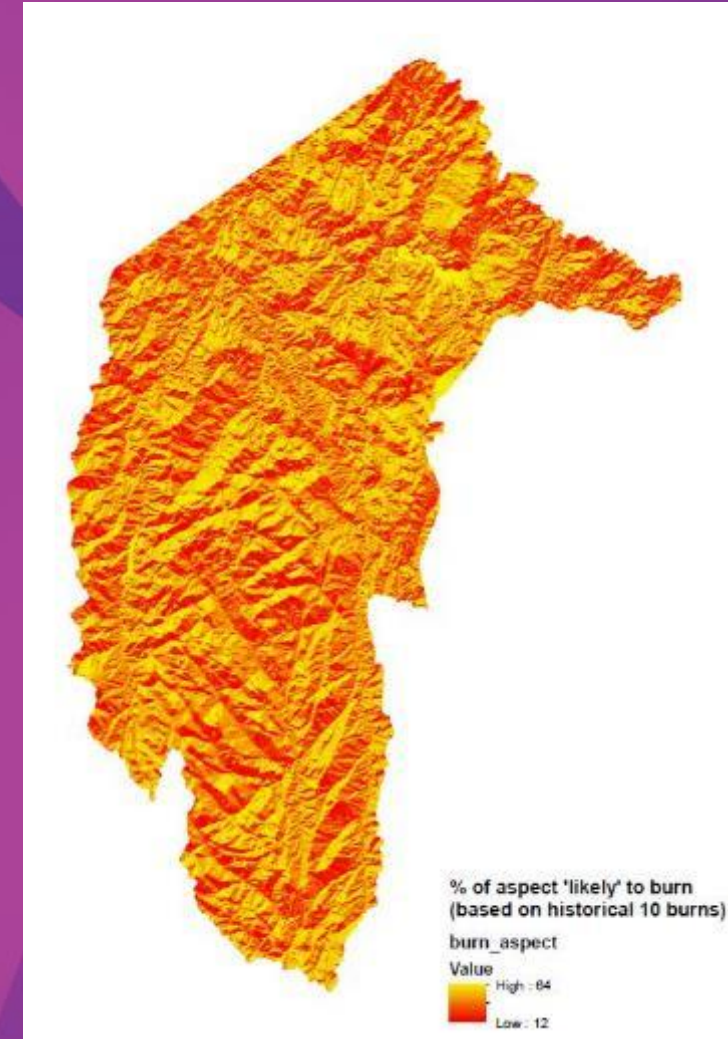




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Why invest in LiDAR for fuel mapping?

3. LiDAR-derived vegetation models can be combined with DEMs to estimate solar radiation and flammability of surface fuels (Nyman et al. 2018).





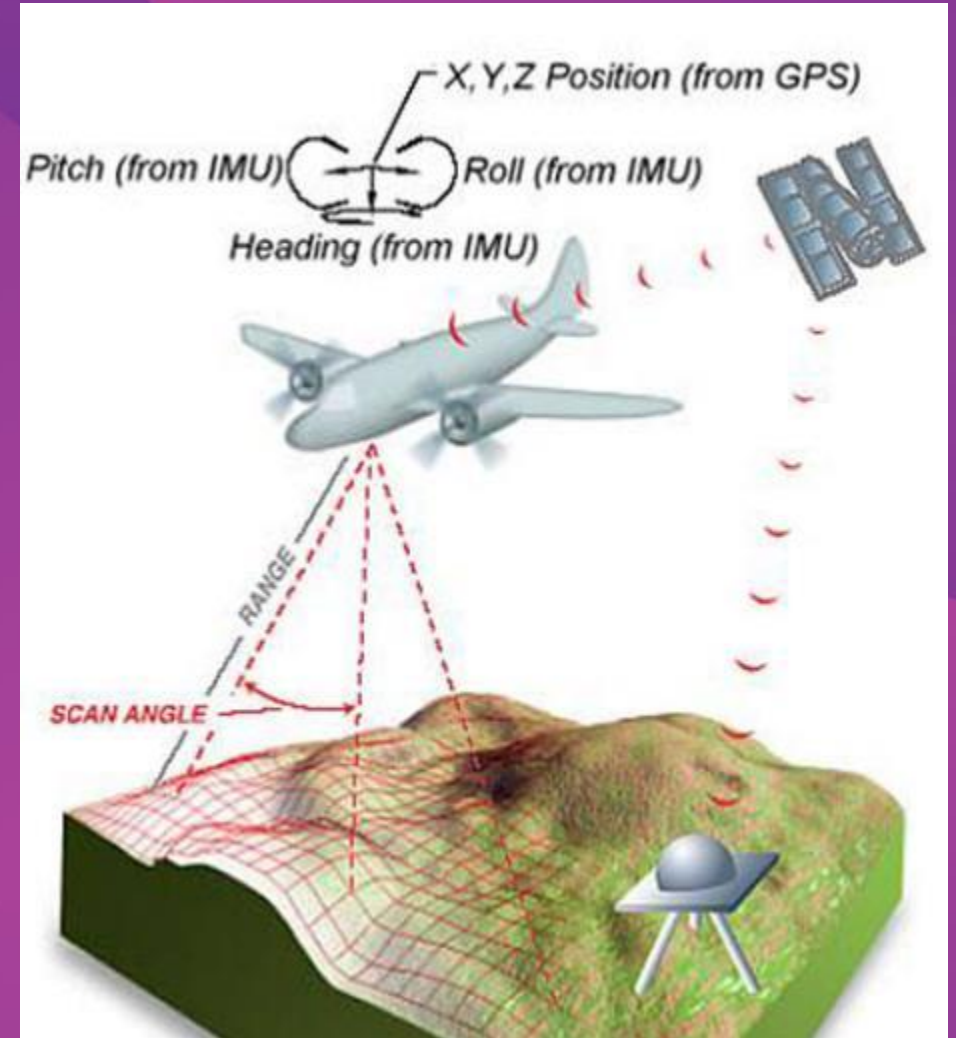
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What is LiDAR?

LiDAR:

Light Detection and Ranging

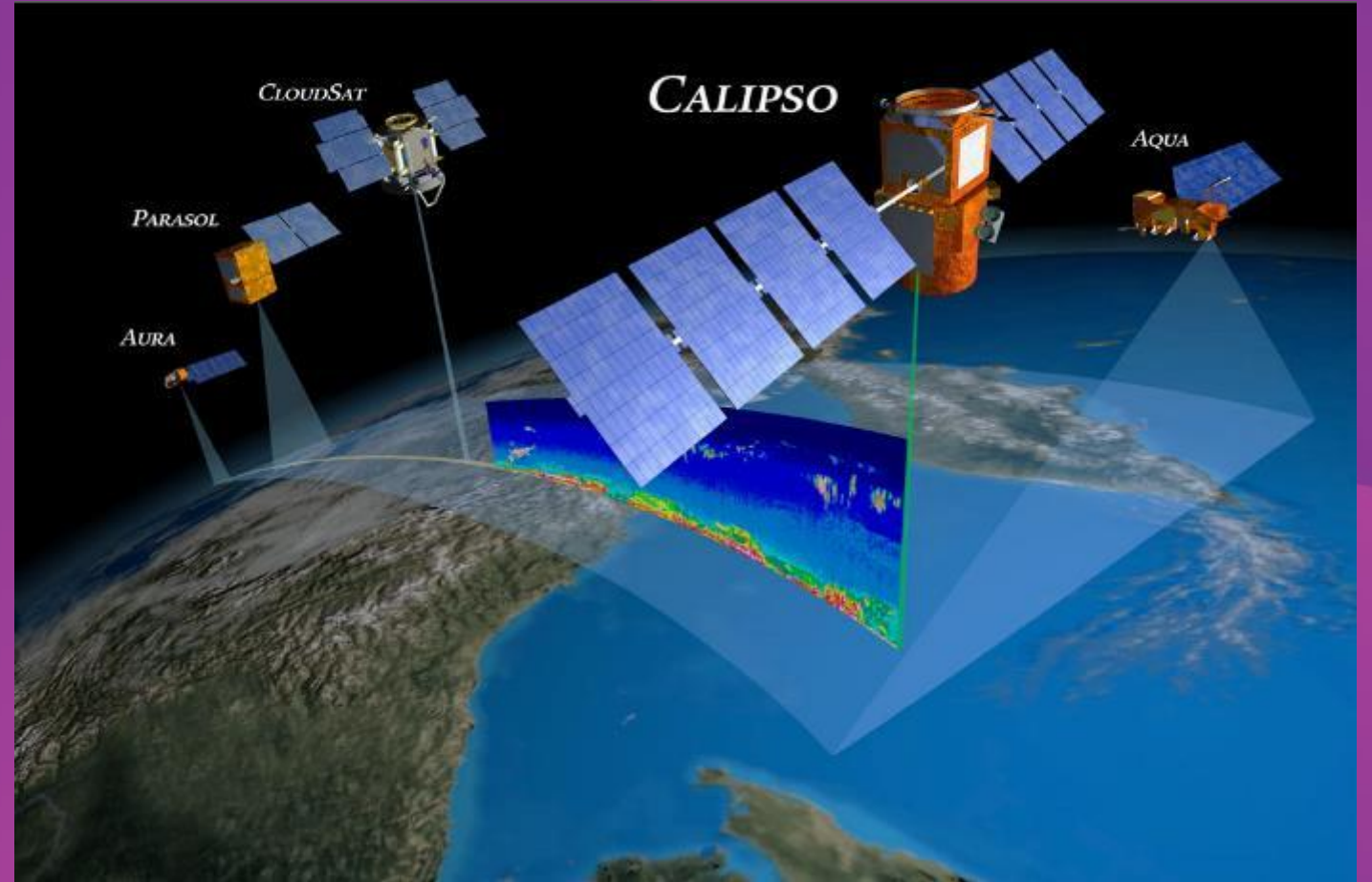
LiDAR is a remote sensing method that uses light in the form of a pulsed laser to measure distances to the Earth.





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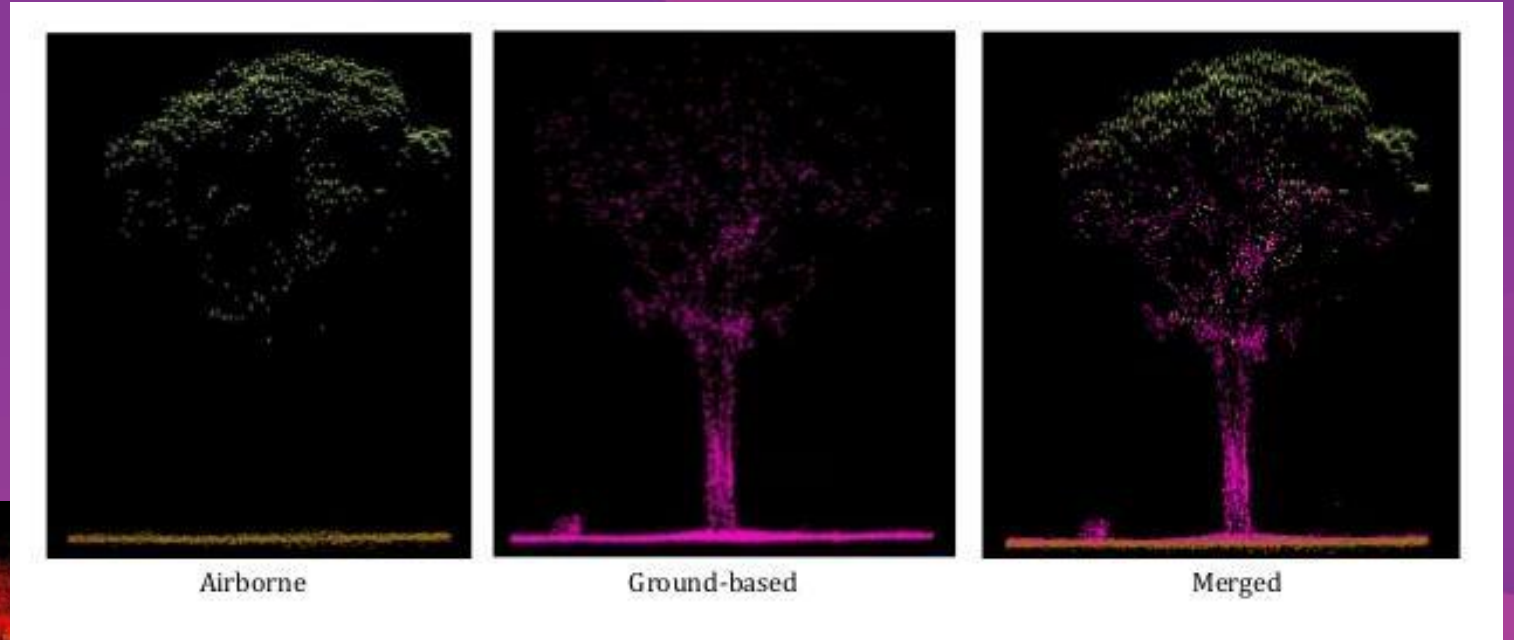
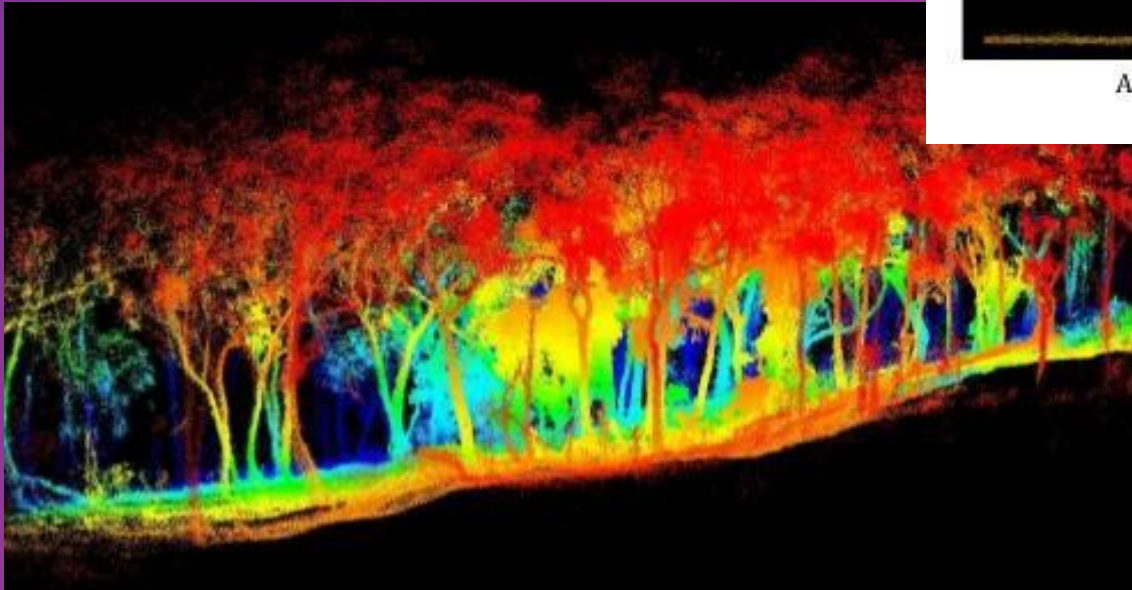
What is LiDAR?





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What is LiDAR?



(Marselis, 2014)



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Acquisition in the ACT

Area: 3272km²

Date: 18 May – 29 July 2015

Pulse density:

Urban = 8ppm

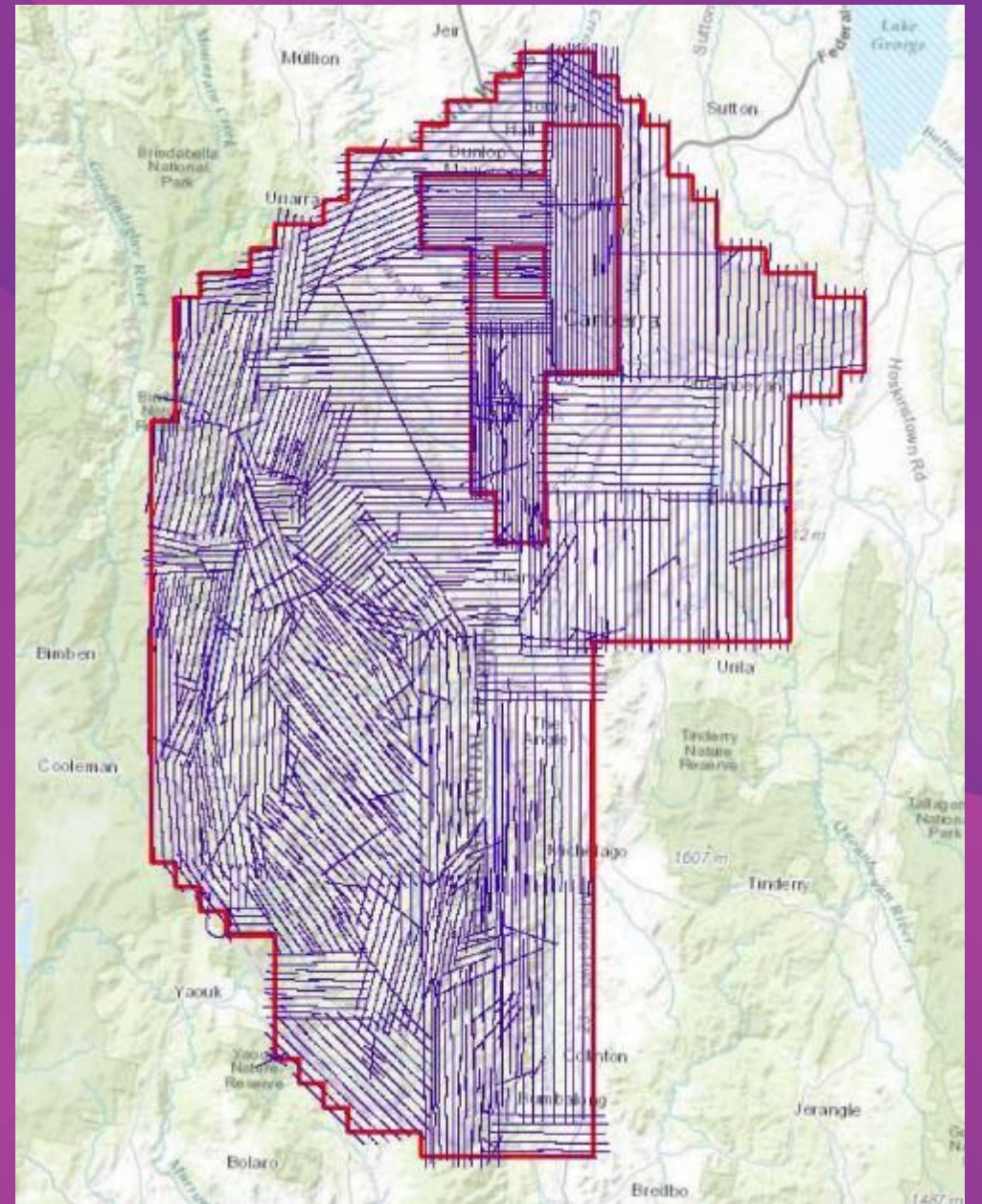
Rural = 4ppm

Average pulse density = 7.9ppm

Vertical accuracy = 0.20m

Cost = \$250,000

(RFS Mapping, 2016)



Flight trajectories



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Acquisition in the ACT

Area: 3272km²

Date: 18 May – 29 July 2015

Pulse density:

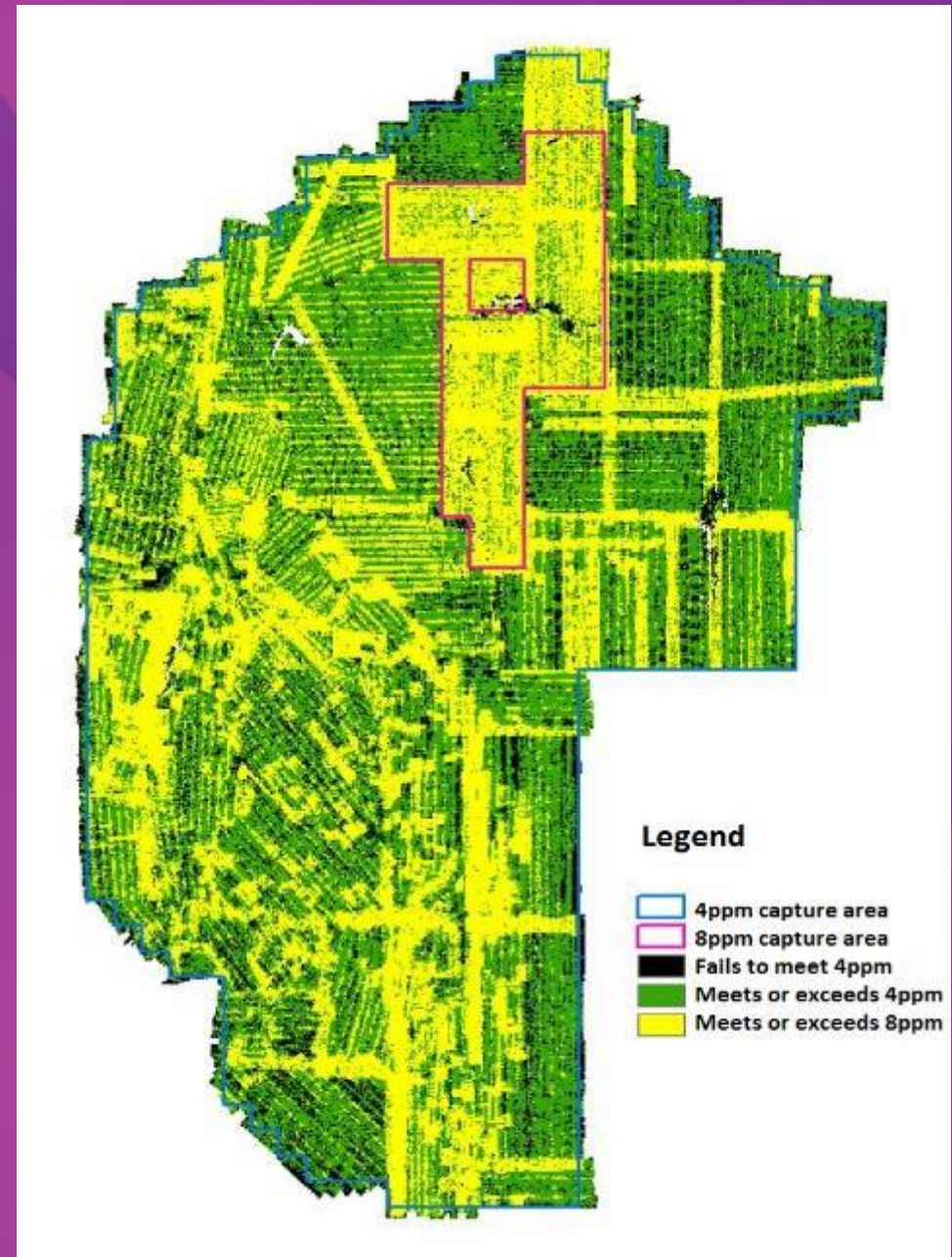
Urban = 8ppm

Rural = 4ppm

Average pulse density = 7.9ppm

Vertical accuracy = 0.20m

Cost = \$250,000



Pulse density



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Contractor processing

Ground classification (ICSM Level 3)

Low vegetation (Level 1)

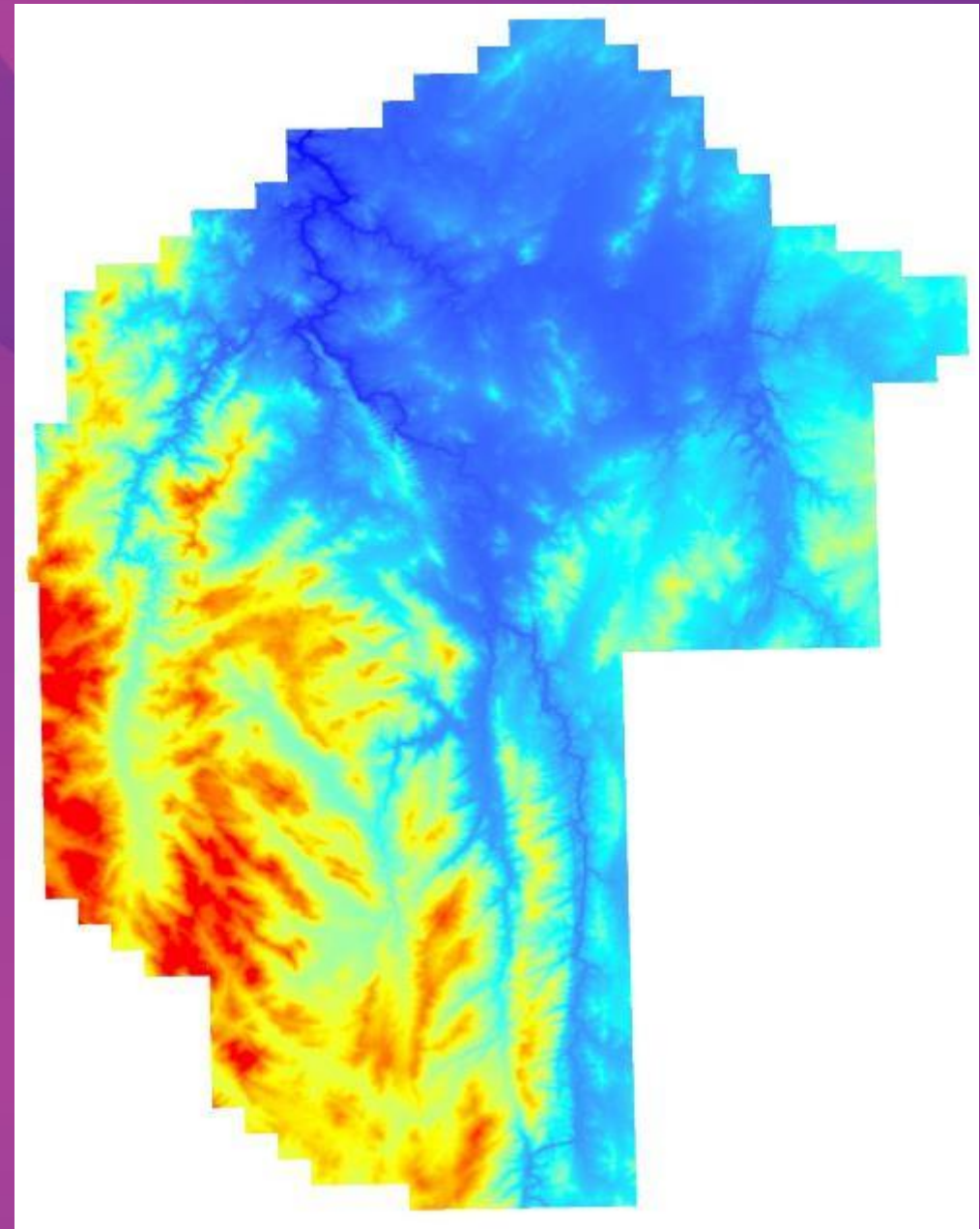
Medium vegetation (Level 1)

High vegetation (Level 1)

Buildings (Level 3)

Water (Level 1)

ICSM = Intergovernmental Committee on
Surveying and Mapping



LiDAR-derived DEM

Contractor processing

ICSM = Intergovernmental Panel on
Surveying and Mapping

Level 0 = Unclassified

Level 1 = Automated

Level 2 = Ground improved

Level 3 = Ground corrected

Level 4 = Detailed correction

Applied to Bushfire Attack Levels (Lhuede et al. 2017)



Fraction Building Footprint



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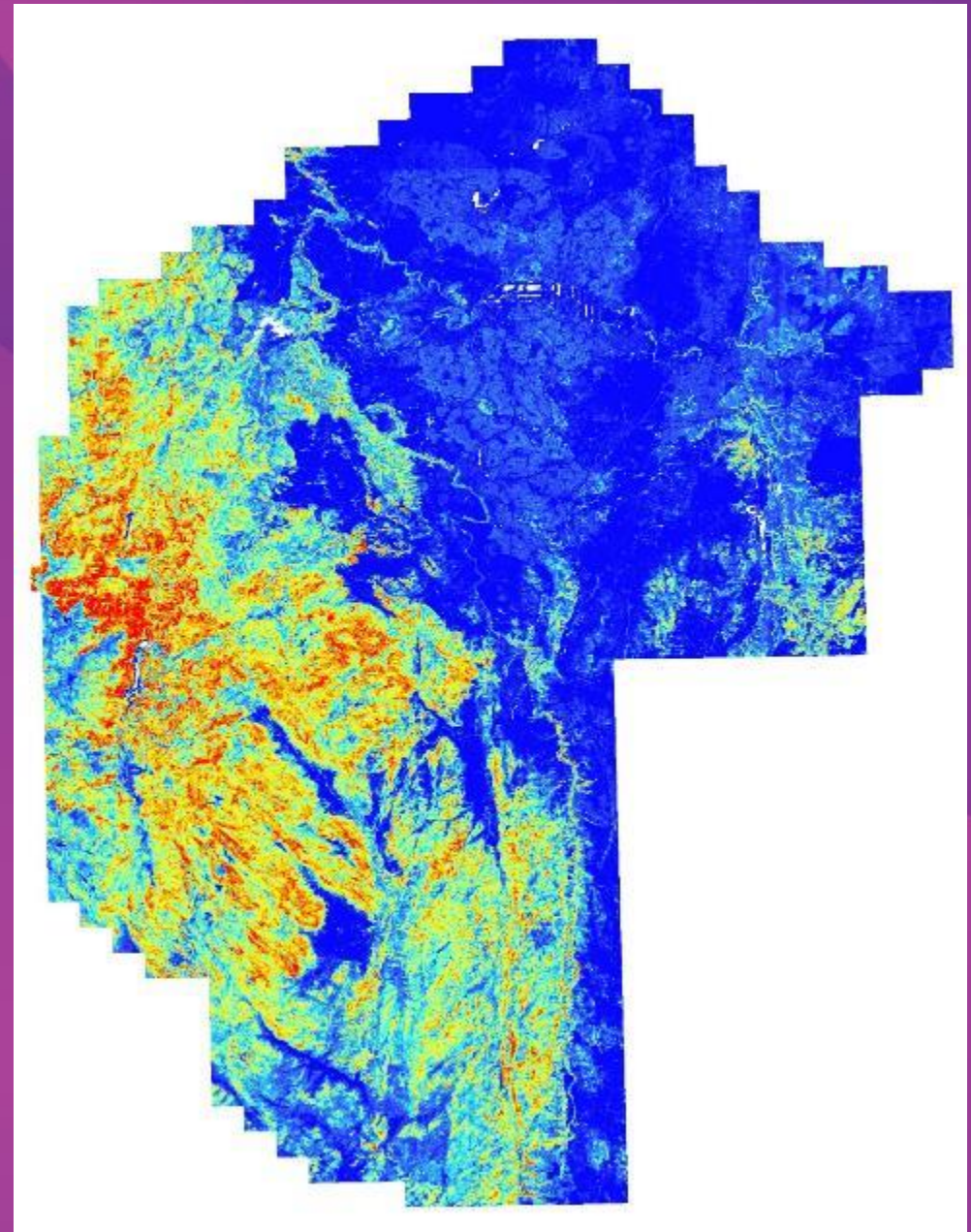
TERN-ANU Processing

AIMS:

1. Develop easily-derived experimental products for land managers.
2. Develop prototype processes and specifications.

OFHA and Project Vesta inputs

(Van Dijk, 2017; Hines et al. 2010; Gould et al. 2007)



LiDAR-derived estimate of Elevated Fuel



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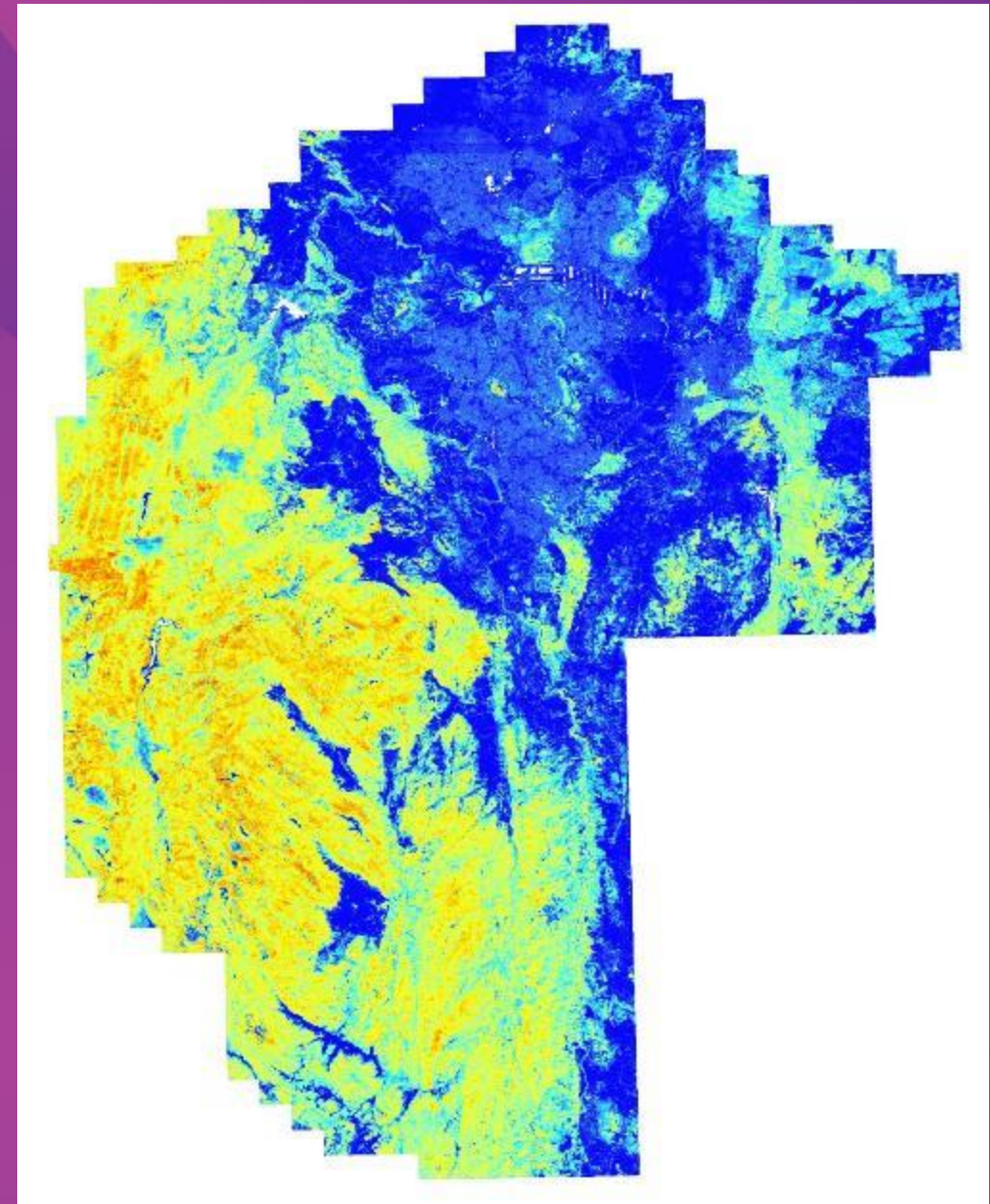
TERN-ANU Processing

Bushfire layers

- Canopy: top and base height
- Elevated fuel – LCF
- Near-surface fuel – LCF
- Overstorey – LCF
- Understorey – LCF

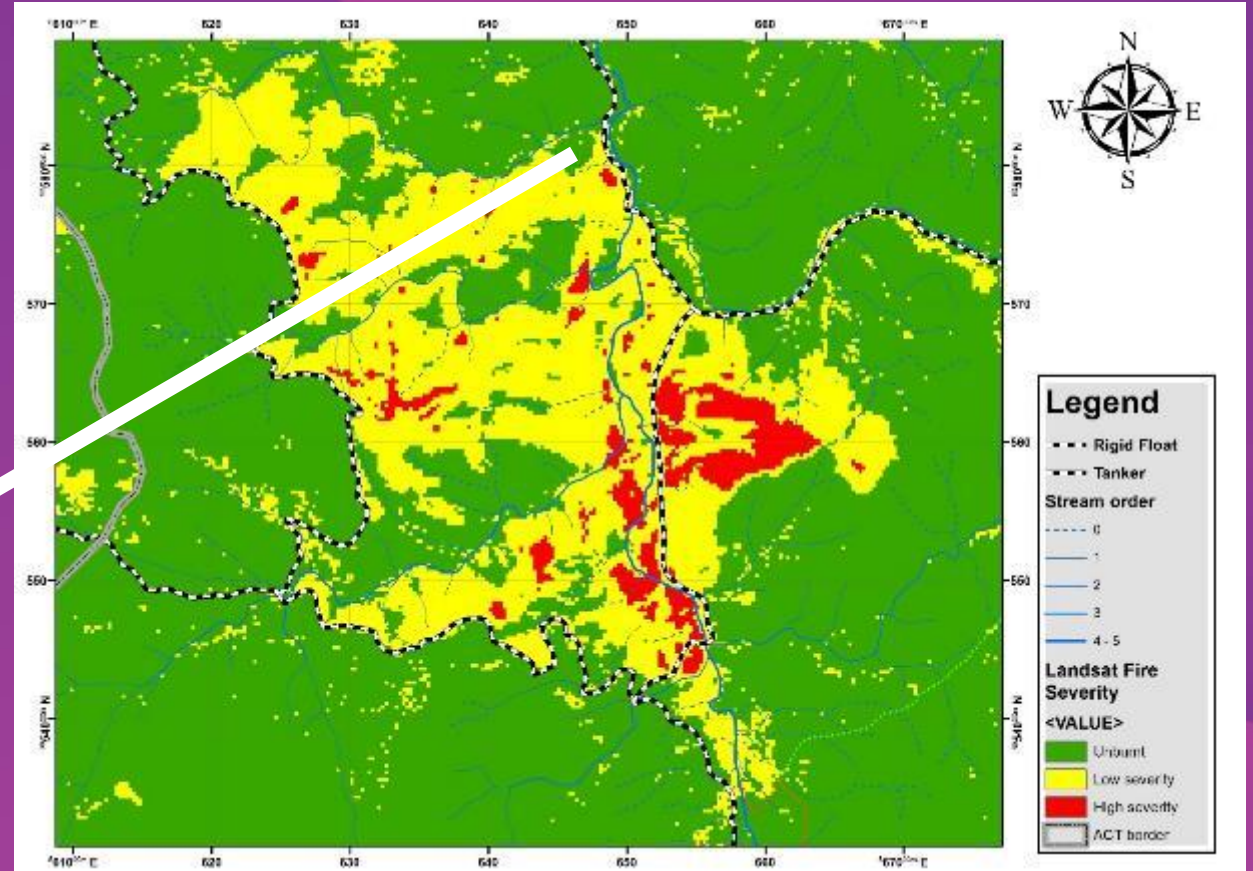
LCF = leaf cover fraction

(Van Dijk, 2017; Hines et al. 2010; Gould et al. 2007)



LiDAR-derived estimate of Near-surface Fuel

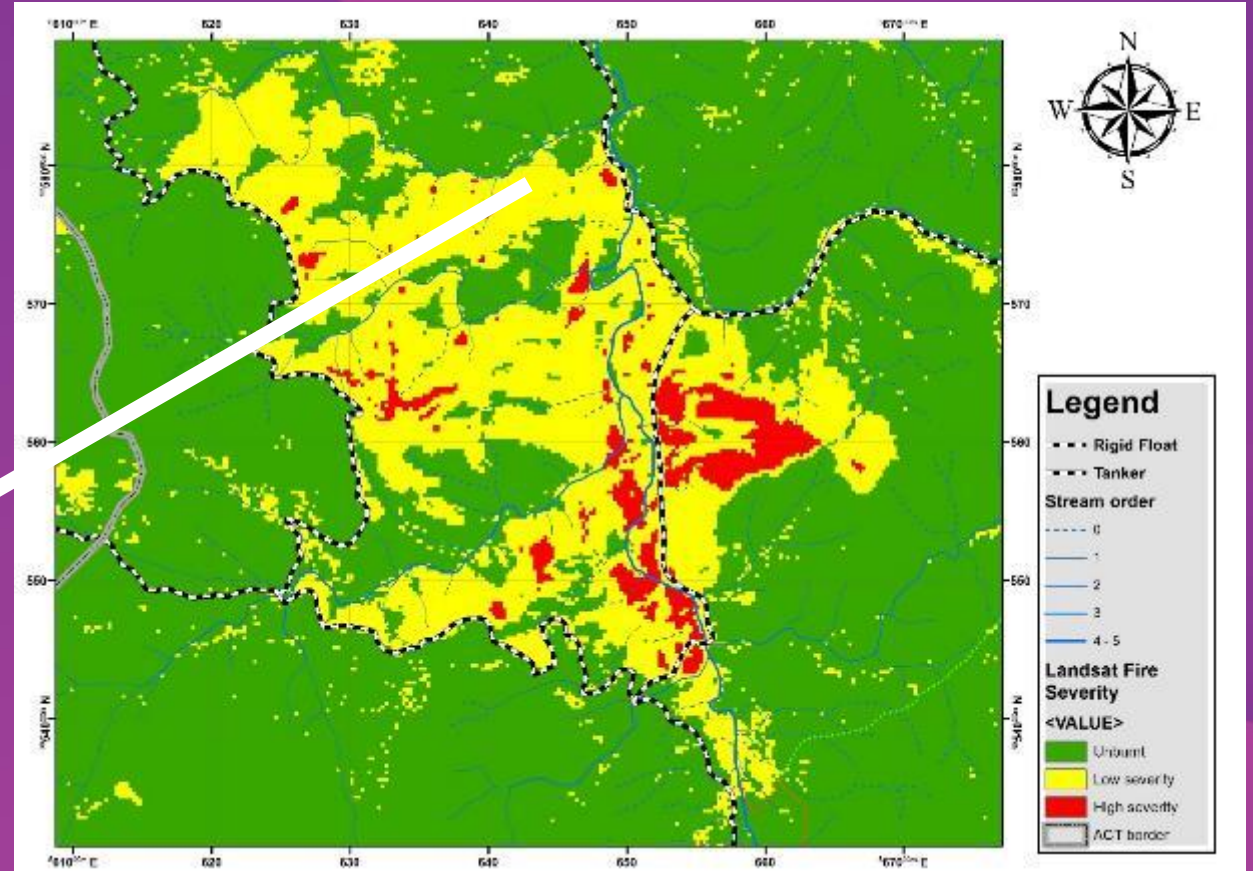
Qualitative truthing



Fire severity analysis of the Cotter River Burn, April 2015

(Leavesley et al. 2015)

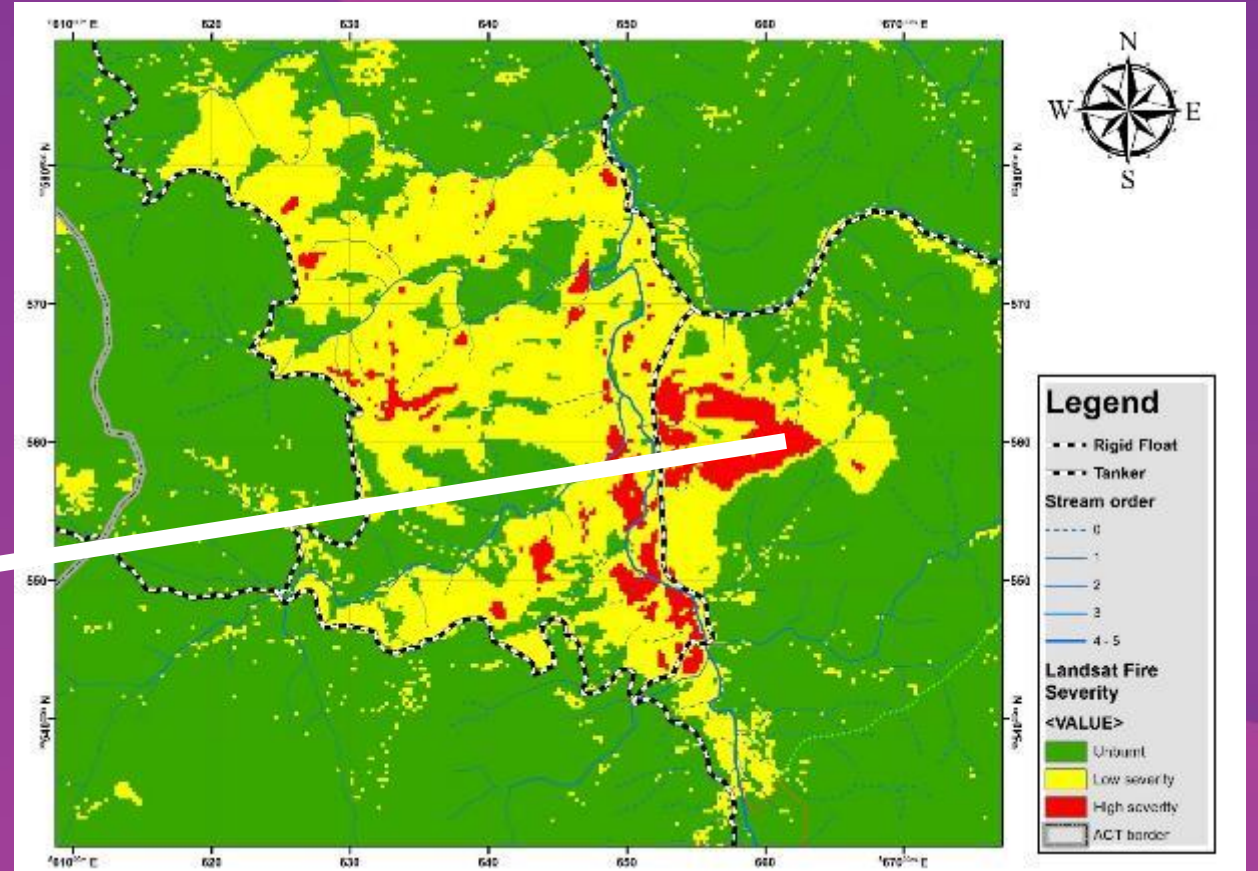
Qualitative truthing



Fire severity analysis of the Cotter River Burn, April 2015

(Leavesley et al. 2015)

Qualitative truthing



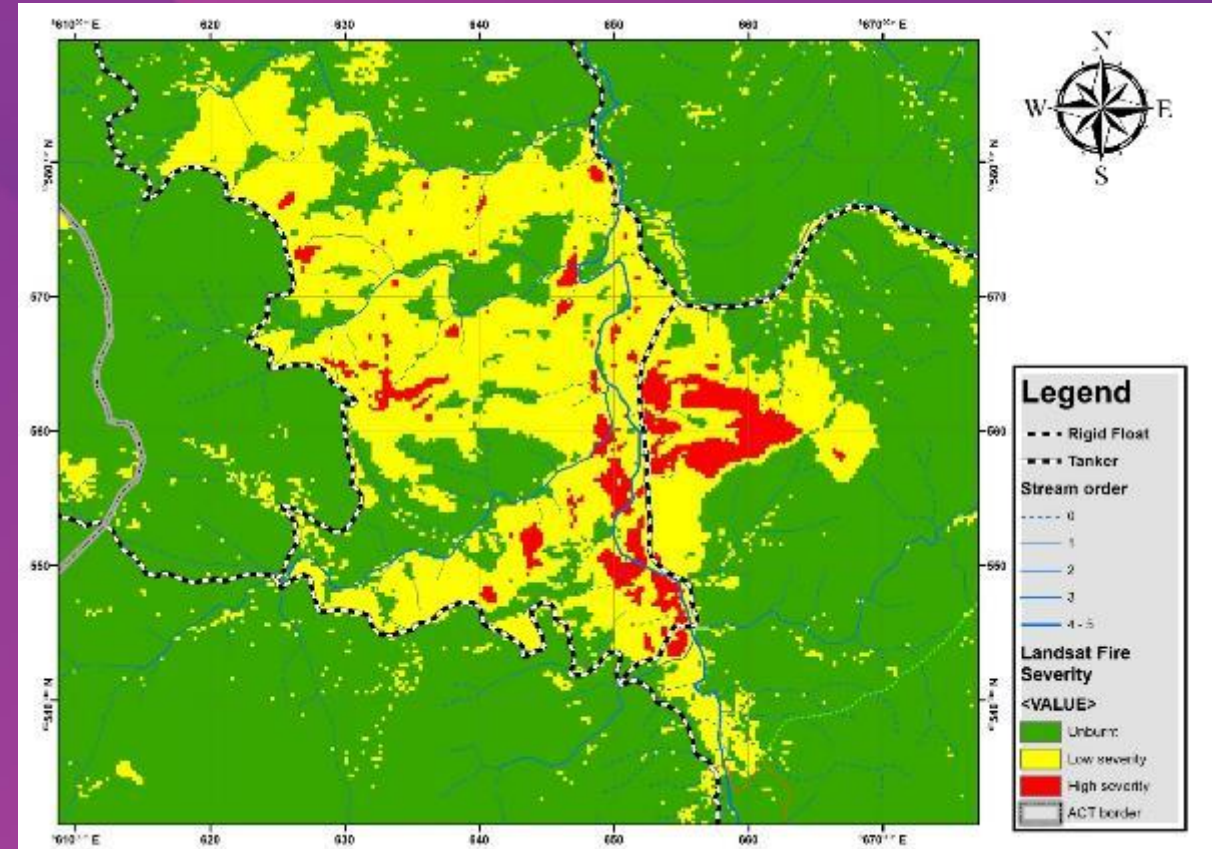
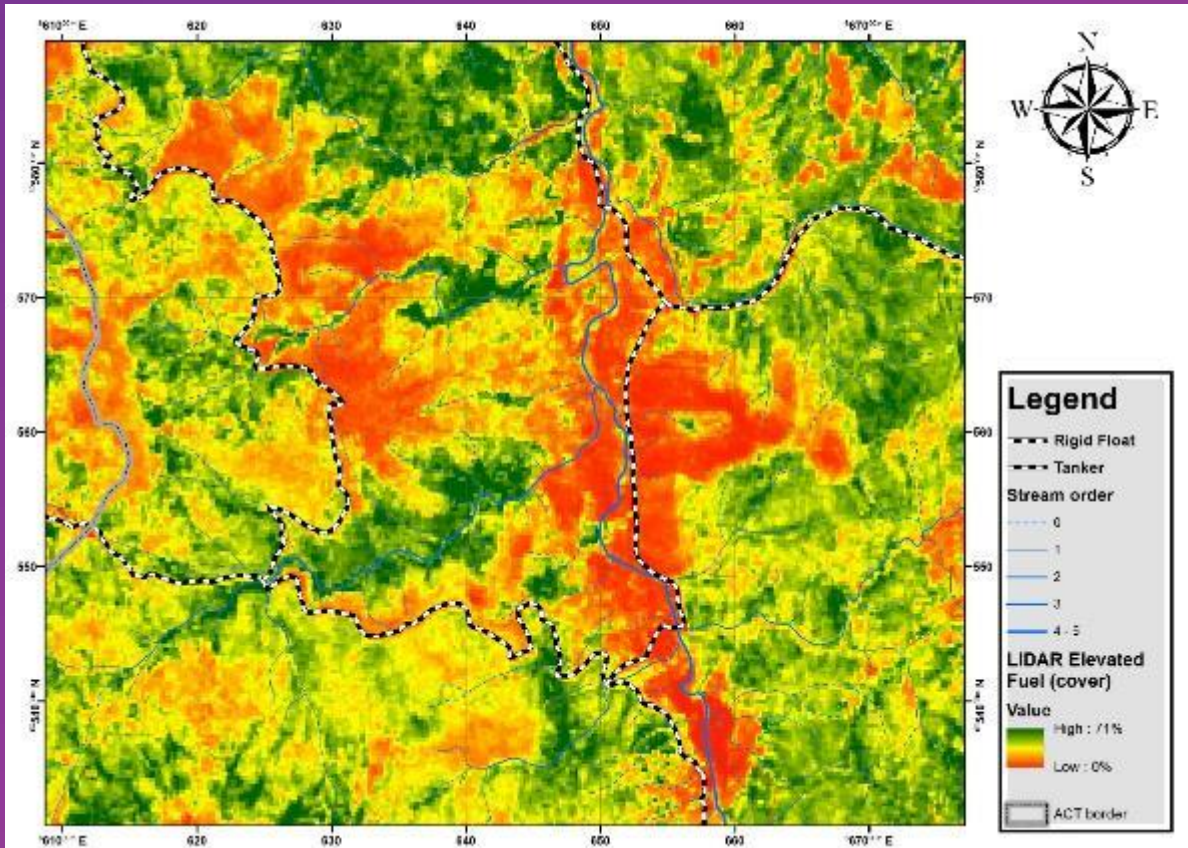
Fire severity analysis of the Cotter River Burn, April 2015

(Leavesley et al. 2015)



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Qualitative truthing



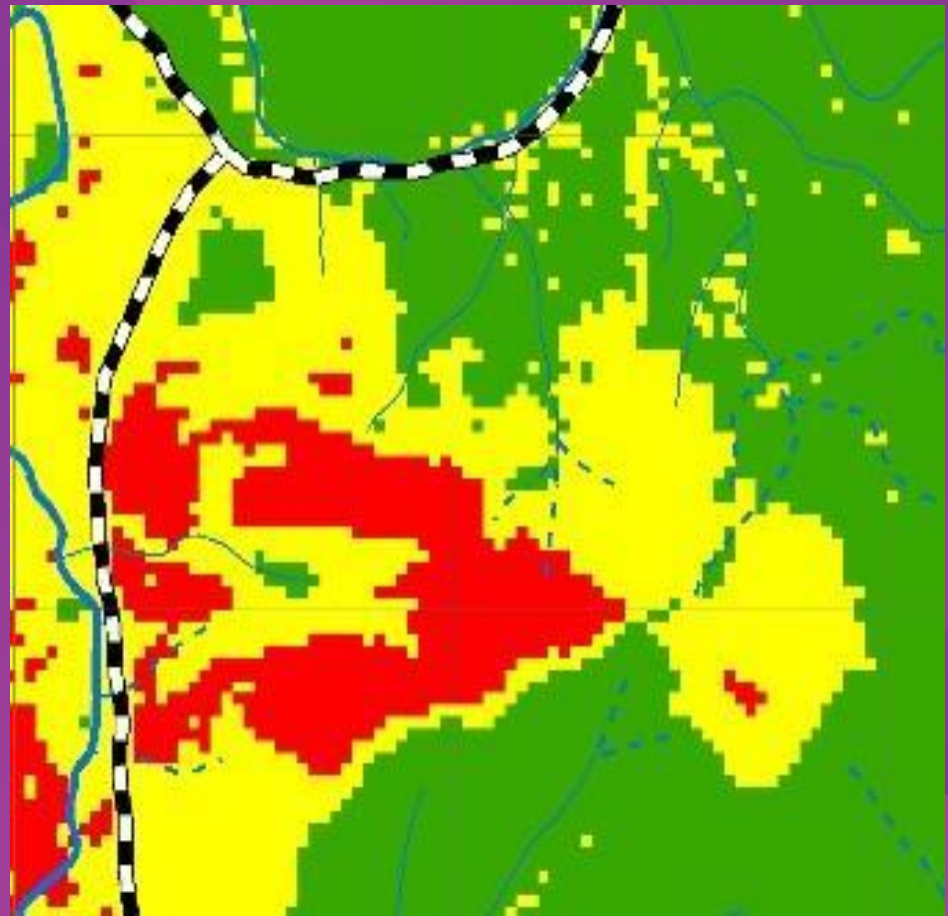
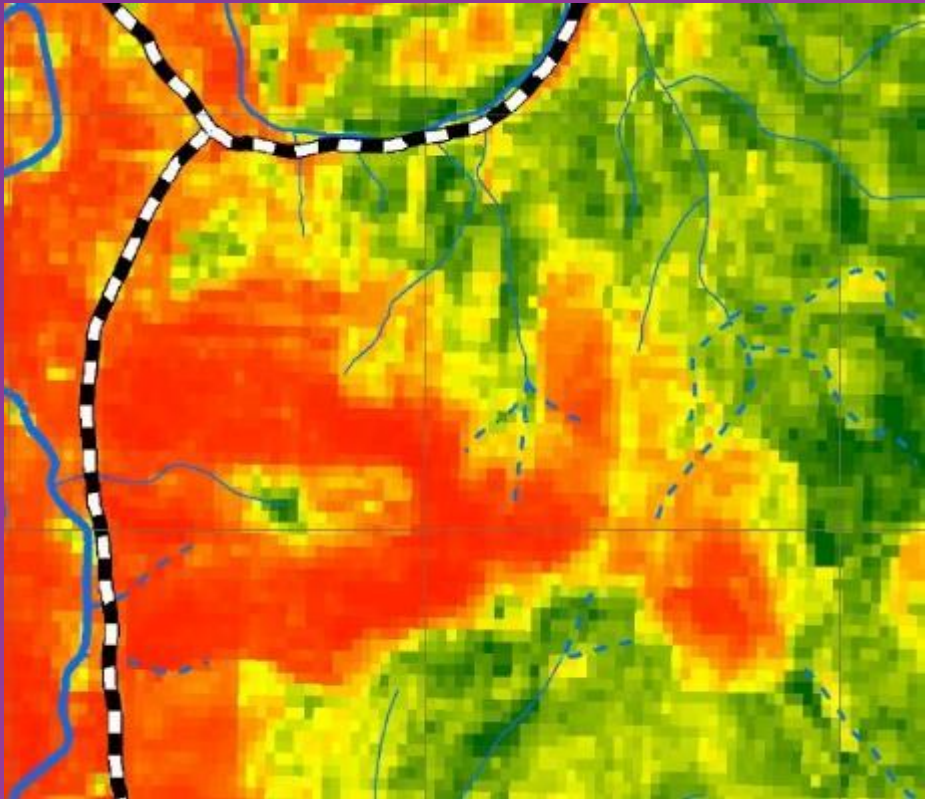
Fire severity analysis, April 2015

LiDAR-derived Elevated Fuel, May-June 2015



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Qualitative truthing



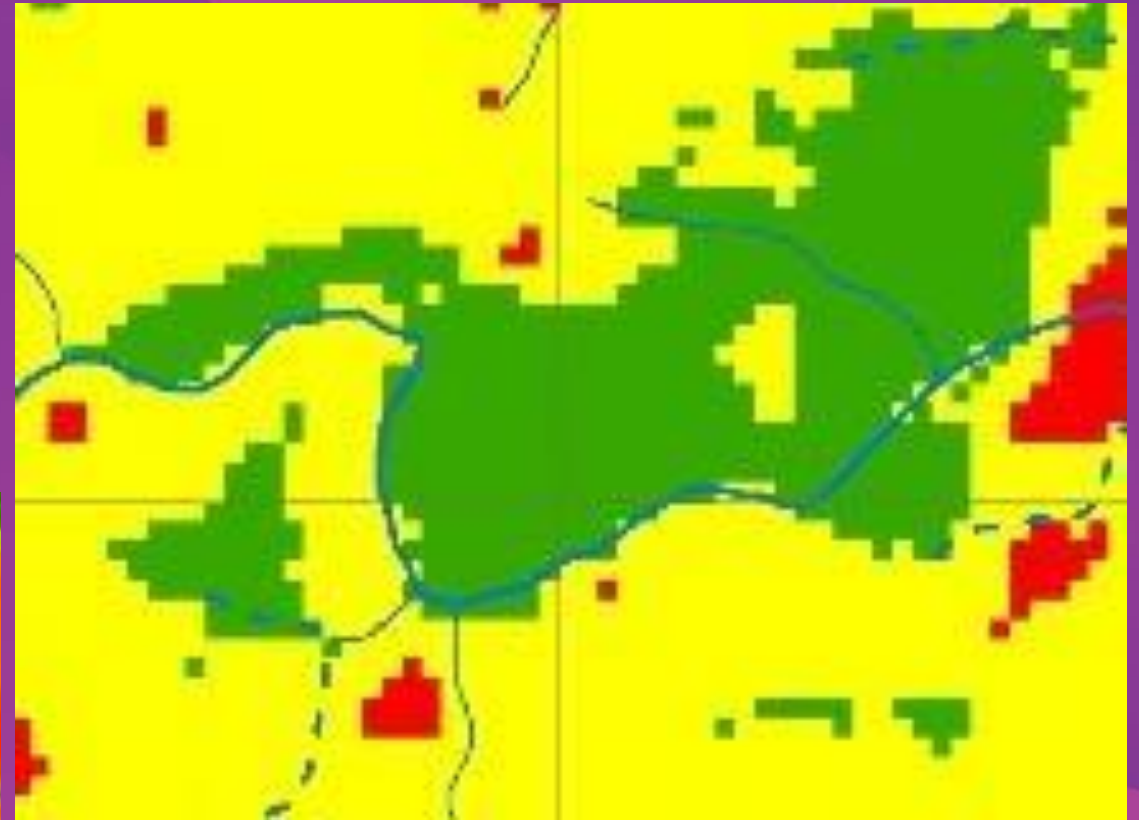
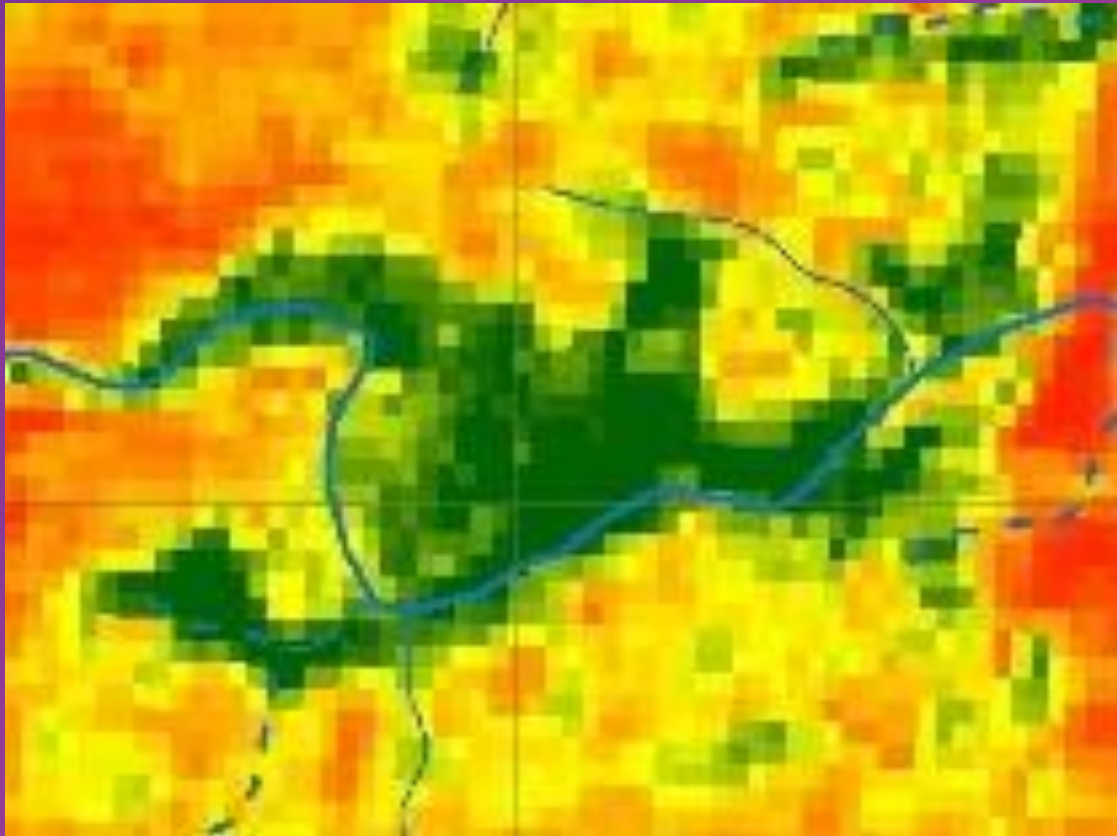
Fire severity analysis, April 2015

LiDAR-derived Elevated Fuel, May-June 2015



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Qualitative truthing



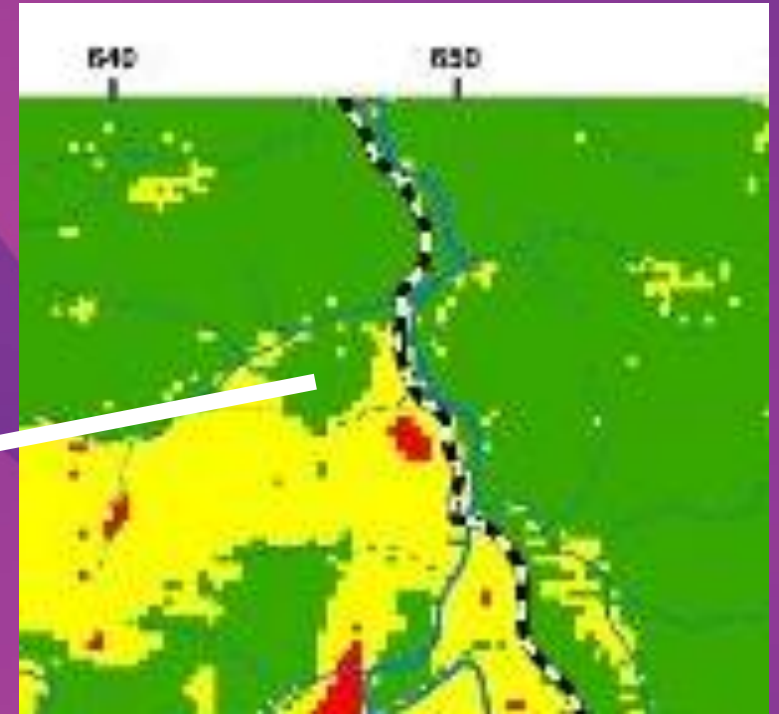
Fire severity analysis, April 2015

LiDAR-derived Elevated Fuel, May-June 2015



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Qualitative truthing



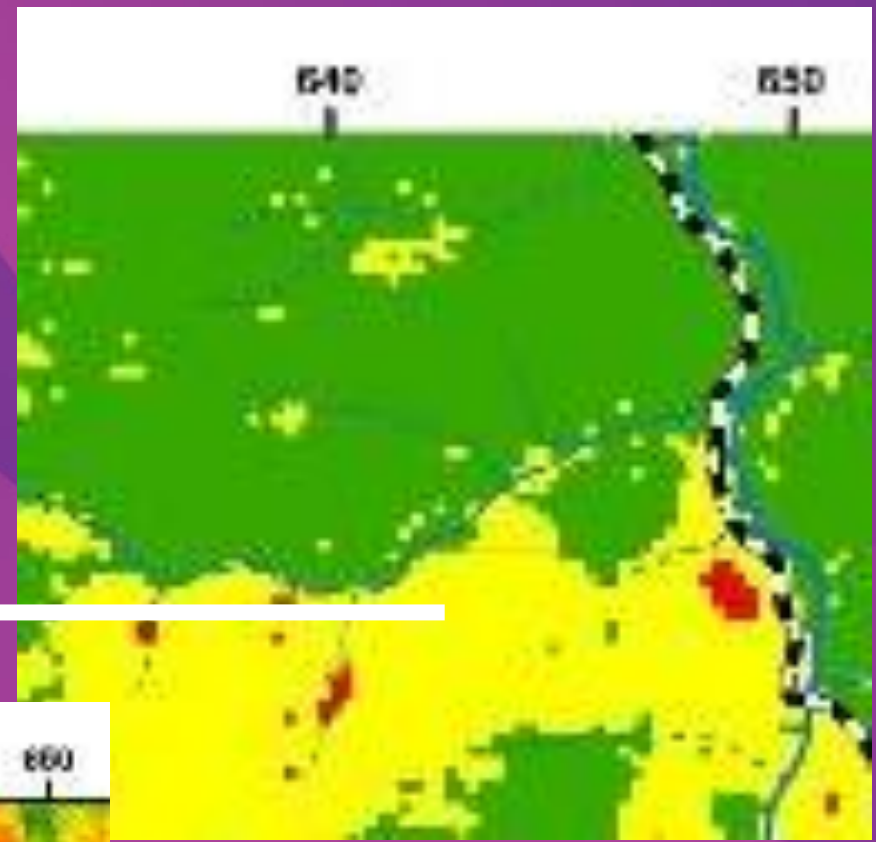
Fire severity analysis of the
Cotter River Burn, April 2015

LiDAR-Derived fuel map,
May-June 2015

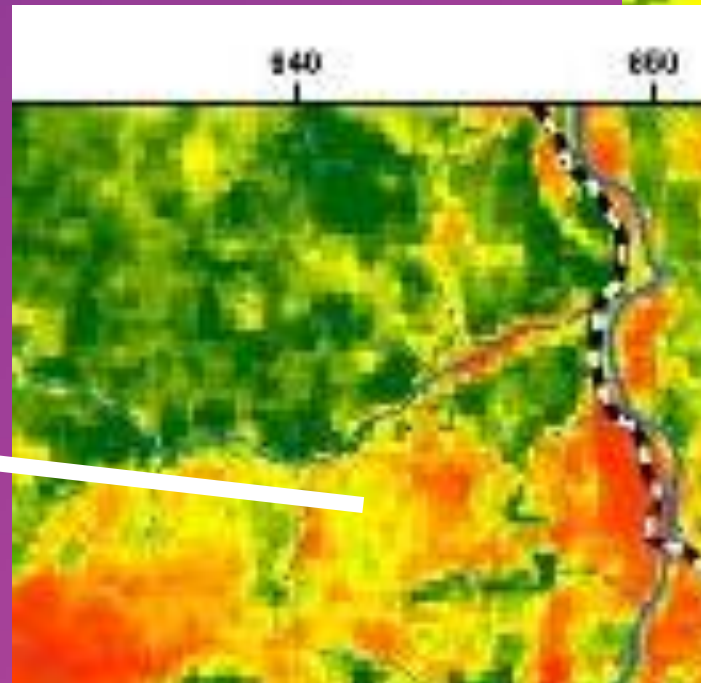


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Qualitative truthing



Fire severity analysis of
the Cotter River Burn,
April 2015

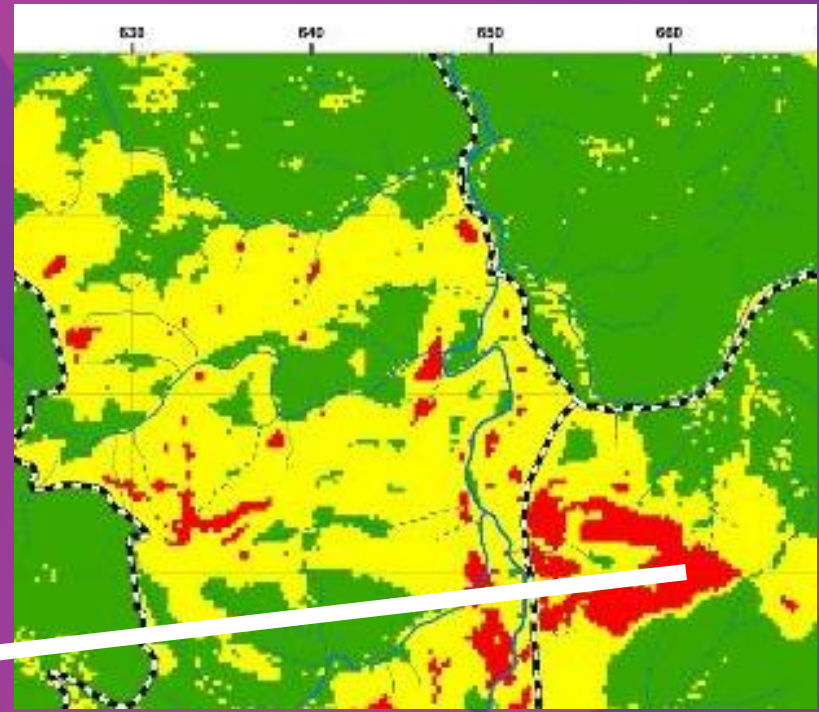


LiDAR-derived fuel map ,
May-June 2015

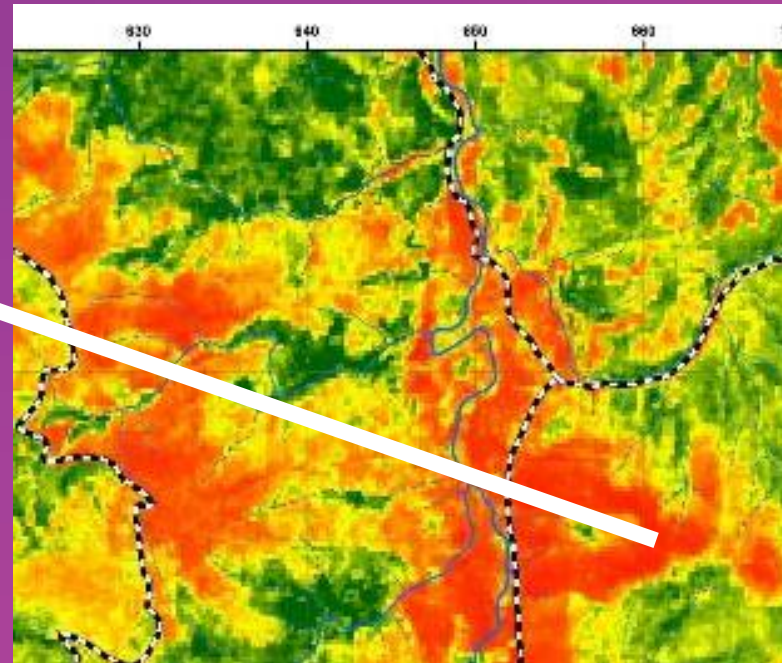


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Qualitative truthing



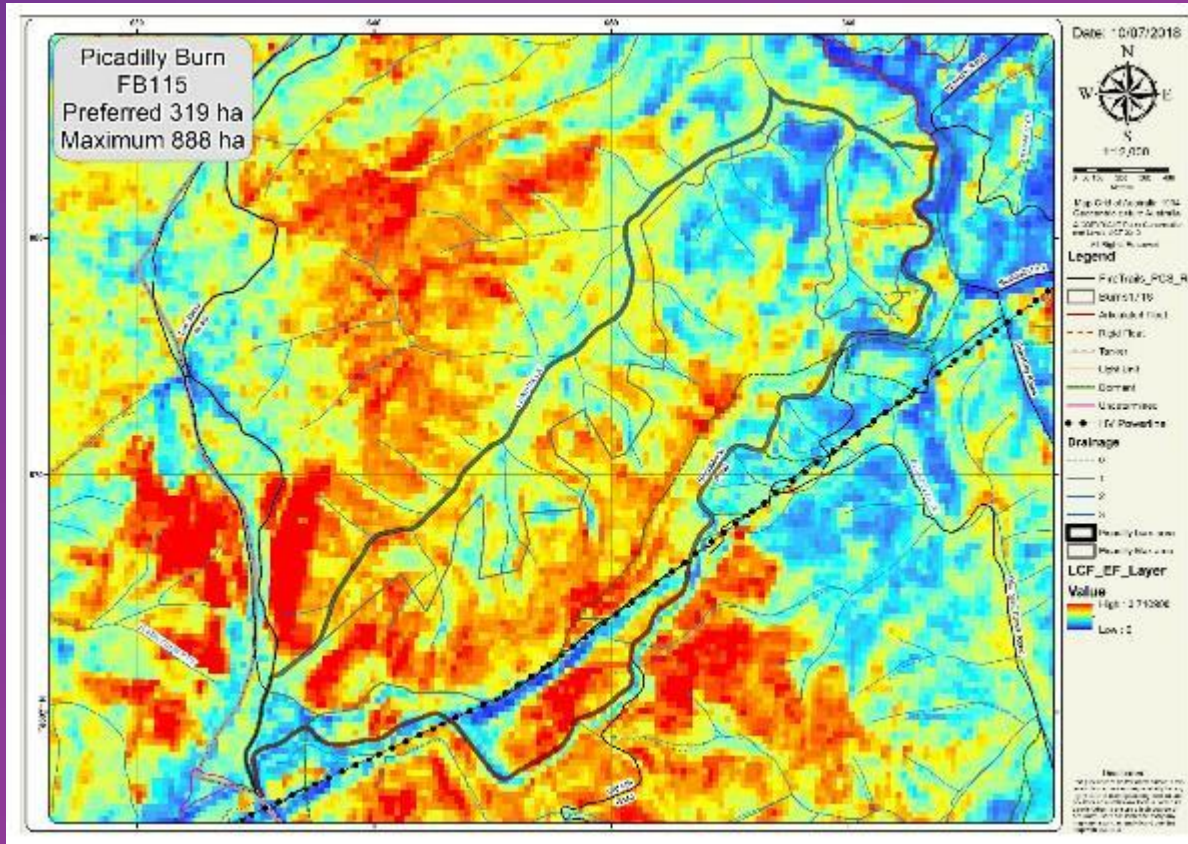
Fire severity analysis of
the Cotter River Burn,
April 2015



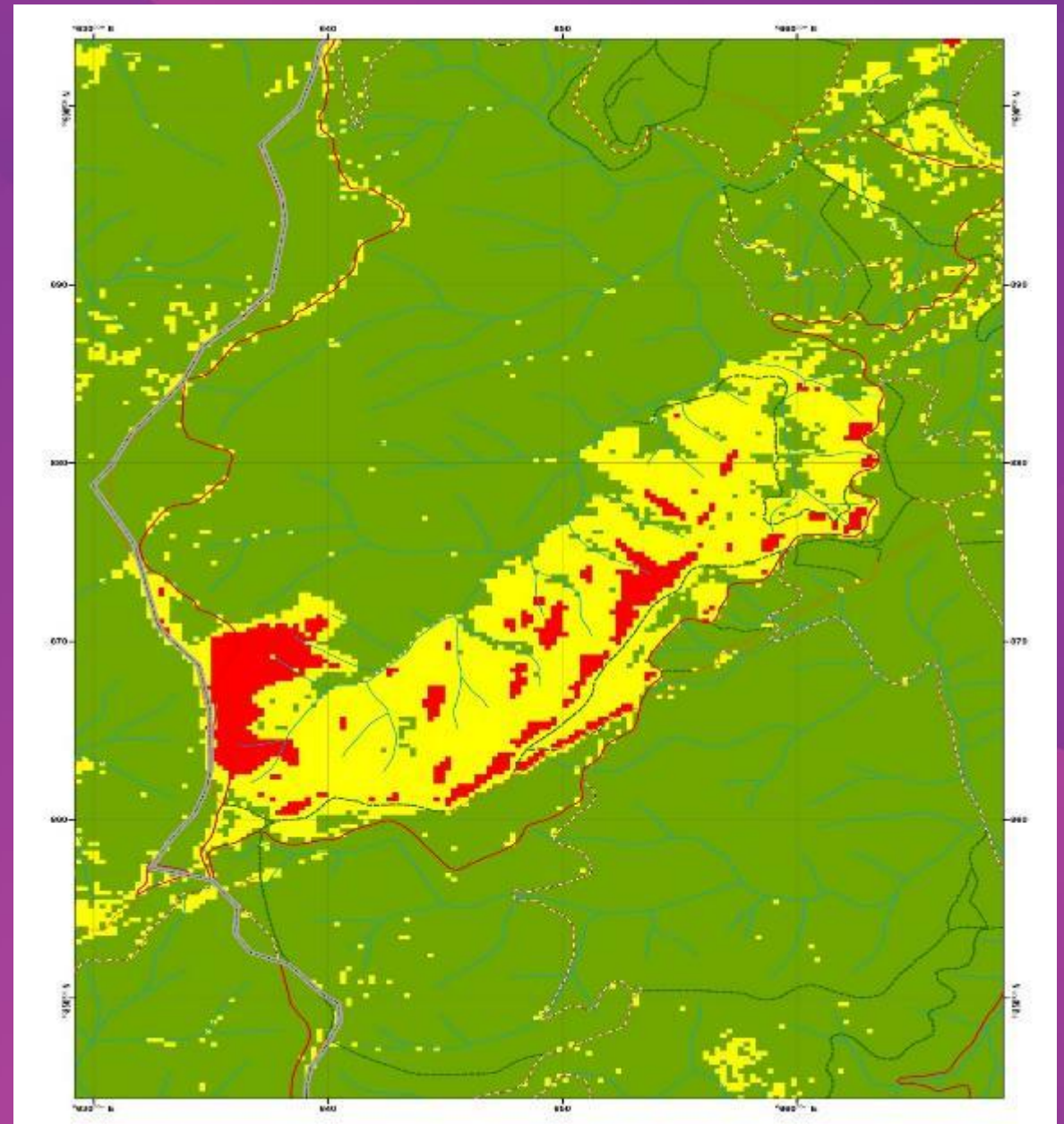
LiDAR-derived fuel
map, May-June 2015



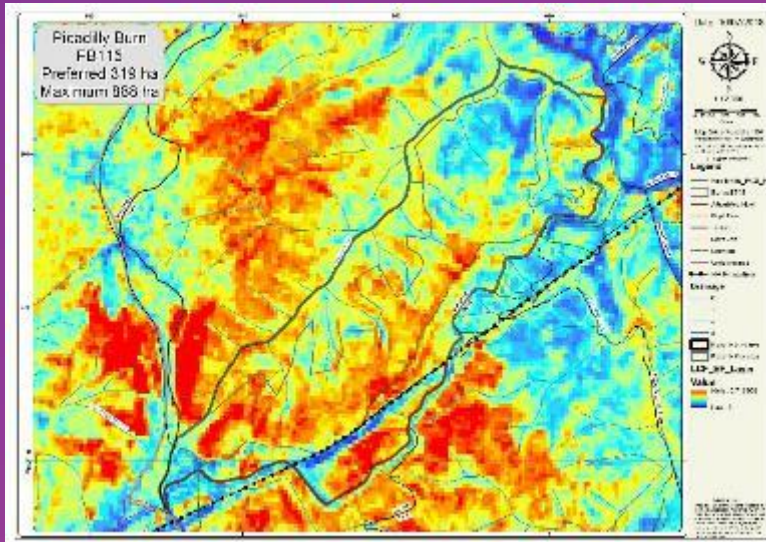
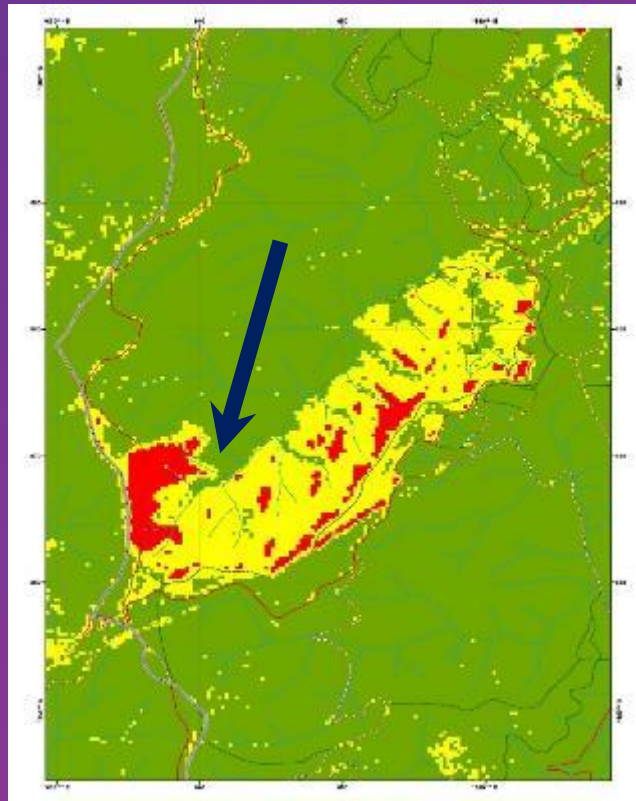
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Piccadilly burn, LiDAR-derived Elevated Fuel



dNBR Fire Severity Assessment, Piccadilly



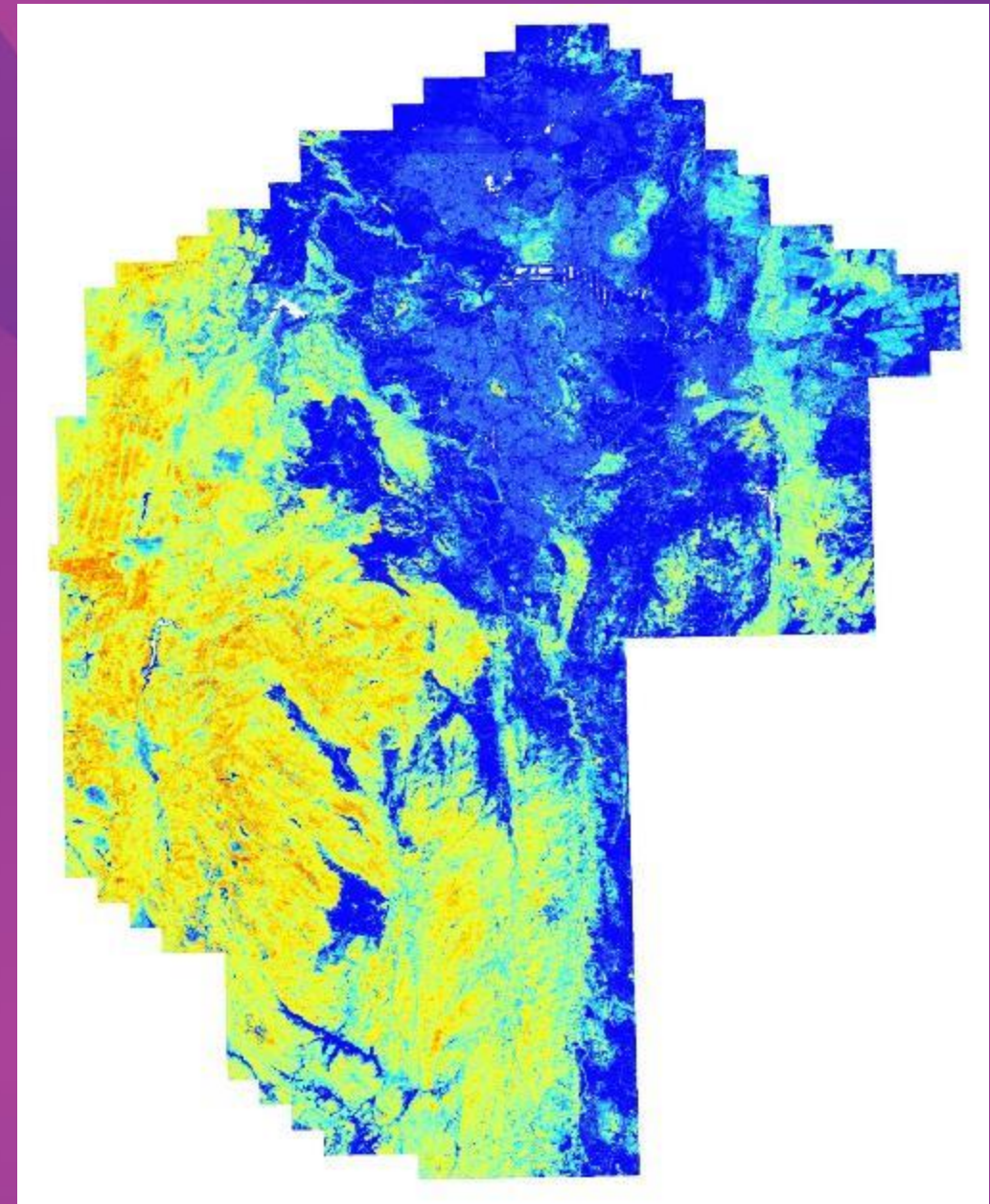


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Wrap up

1. Generally suitable for fuel mapping, but...
2. ... issues with bark and litter.
3. Suitable for fuel, carbon and post-burn hydrology
4. Low frequency suitable for burn planning?

5. Move to “remote-sensing enabled systems”



LiDAR-derived estimate of Near-surface Fuel