

# Fire Surveillance and Fuel Hazard Mapping

Research advisory forum / **2018**

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**Brad Davies** /NSW RFS

**Dr. Stuart Matthews** /NSW RFS

**Dr. David Hudson** /Geoscience Australia



**Business**  
Cooperative Research  
Centres Programme

# Research Translation – Fuels3D\*

RESEARCH

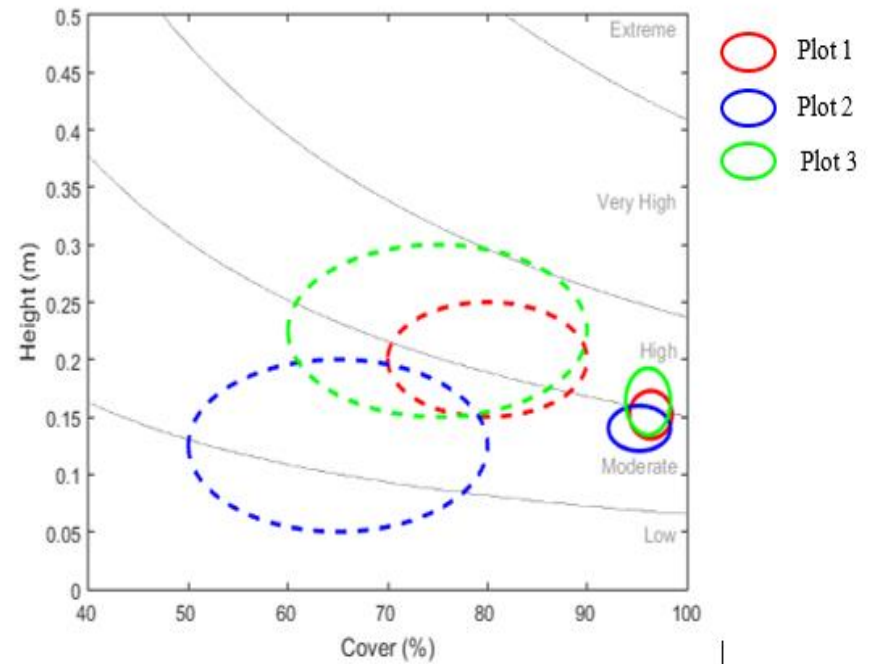
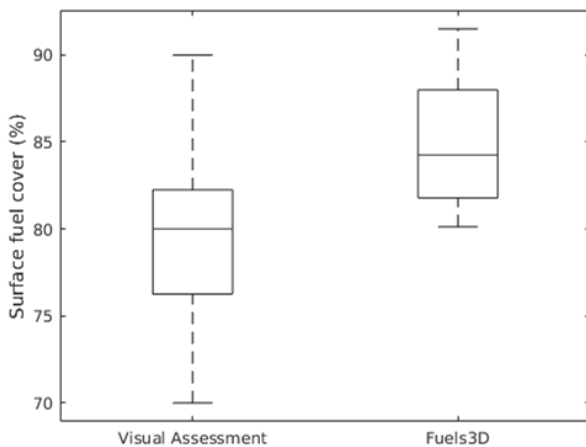
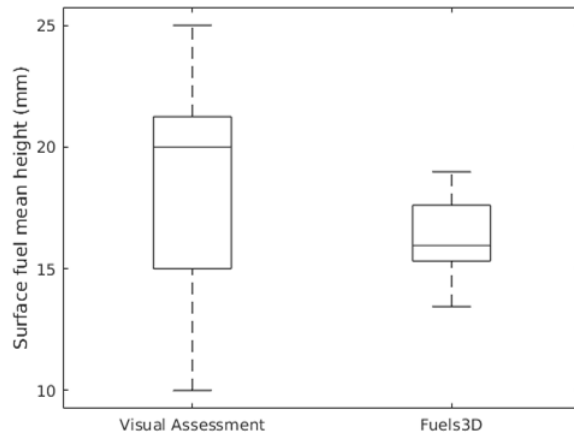
UTILISATION

Problem	Opportunities	Solution	Benefits	End-User Community
<p>Lack reliability of field fuel hazard assessments = poor data quality and <u>low information value</u>.</p> <p>Fire behavior and fire spread models <u>require quantifiable measures</u> of fuel hazard elements.</p> <p>Data collection devices such as LiDAR based technologies for quantifying fuel structure on the ground are <u>expensive and sensitive to wind</u>.</p>	<p>Bring together off-the-shelf cameras and smartphones with advances in computer vision / photogrammetry.</p> <p>Suitable for UAV platforms.</p> <p><b>Research Outputs</b></p> <p>6 peer-reviewed journal publications, 3 new publications in review.</p> <p>VSEA (environment and sustainability) winner.</p> <p>3 PhD students.</p>	<p>Complements existing fuel hazard assessments.</p> <p>Uses off-the-shelf cameras and smartphones.</p> <p>Tool chain from images to 3D point cloud coupled with workflow for extracting fuel layers and calculating quantifiable surface and near-surface fuel structure metrics.</p>	<p>Cheap, rapid, easy-to-use, repeatable.</p> <p>Quantifiable metrics per fuel strata.</p> <p>Adaptable to new research and tech.</p> <p><b>Utilisation Activities</b></p> <p>Two end-user utilisation trials with end-users from across Australia.</p> <p>In-field, multi-tech case studies across priority landscapes.</p>	<p>State land management, and emergency service agencies.</p> <p>AFAC.</p> <p>Local councils.</p> <p>Fire behavior and fire spread modellers.</p>
<p><b>What has been achieved?</b></p> <p>Proof-of-concept and testing.            Accuracy assessment and technology comparison            Bespoke and novel algorithms for extracting fuel layers.            Solution workflow design - hardware and software.</p>		<p><b>What next?</b></p> <p>Funding ceases December 2018 (*half project).            Seeking investment for continuation.</p>		



# Fuels3D

Understanding the problem



# Fuels3D

Providing a solution



Field  
image capture

Image transfer  
(from end-  
user)

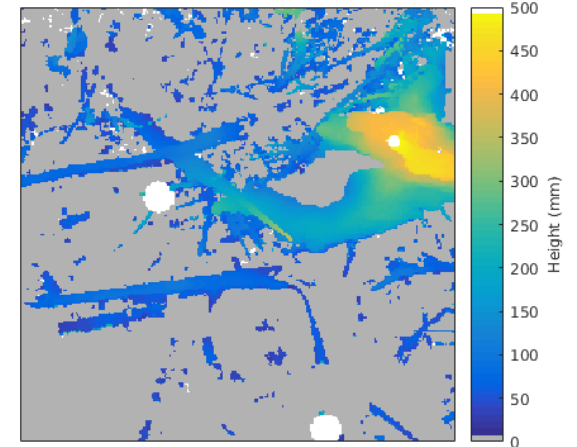
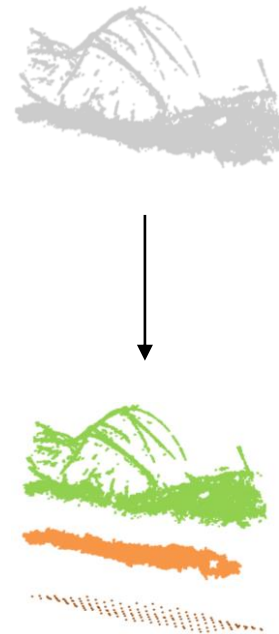
Image  
matching and  
scale

3D point  
creation

Fuel layer  
extraction

Calculate fuel  
metrics and  
maps

Data transfer  
of metrics (to  
end-user)



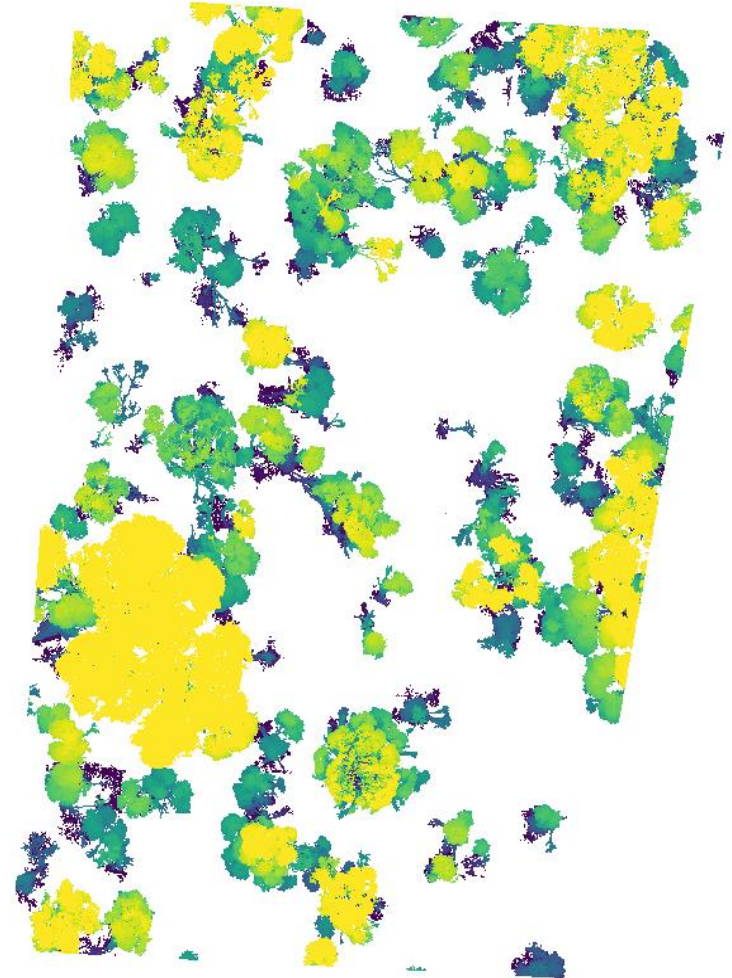
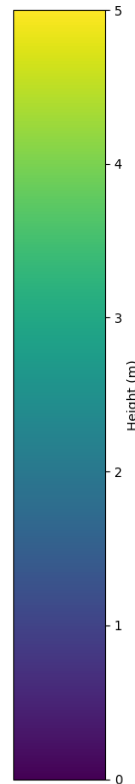
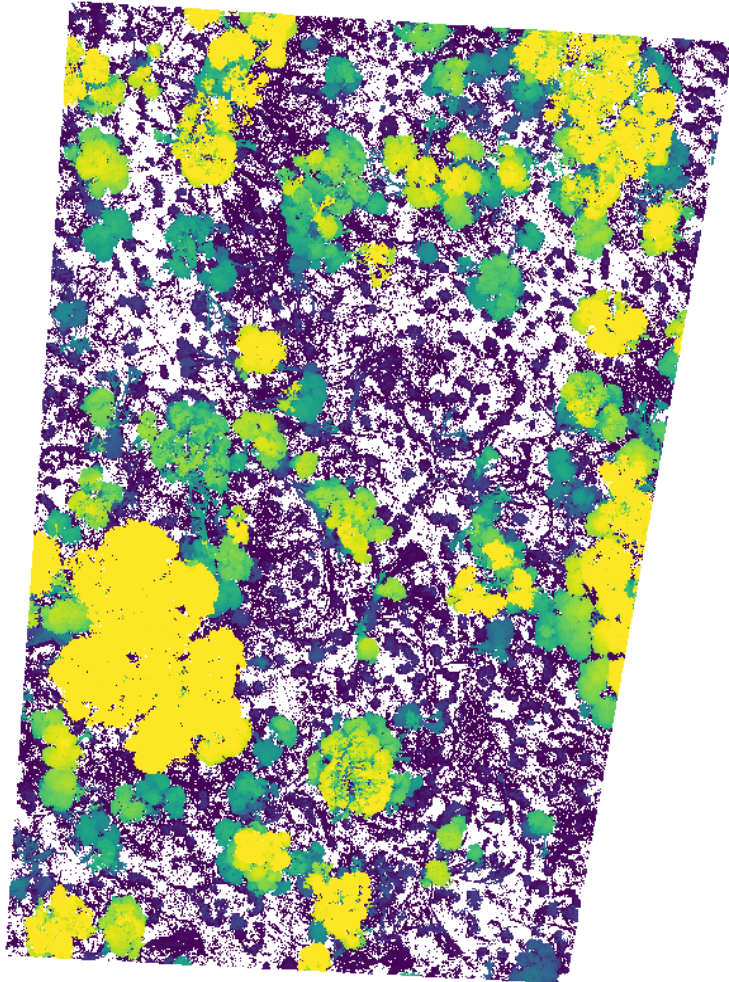






# Fuels3D

Data outputs



# Fuels3D

Where to next?



- Automating the end-to-end workflow.
- Fuels3D stick: multi-band, multi-camera image capture device.
- Solid state LiDAR.
- UAV mounted or aerial Fuels3D.
- Fuel structure and hazard change mapping, pre and post burn measurement.
- Bark hazard and new metrics for vertical connectivity.
- Protocols for technology limits for data capture under varying environmental (e.g. wind and illumination) conditions.

# Research Translation – Fire Surveillance

RESEARCH

UTILISATION

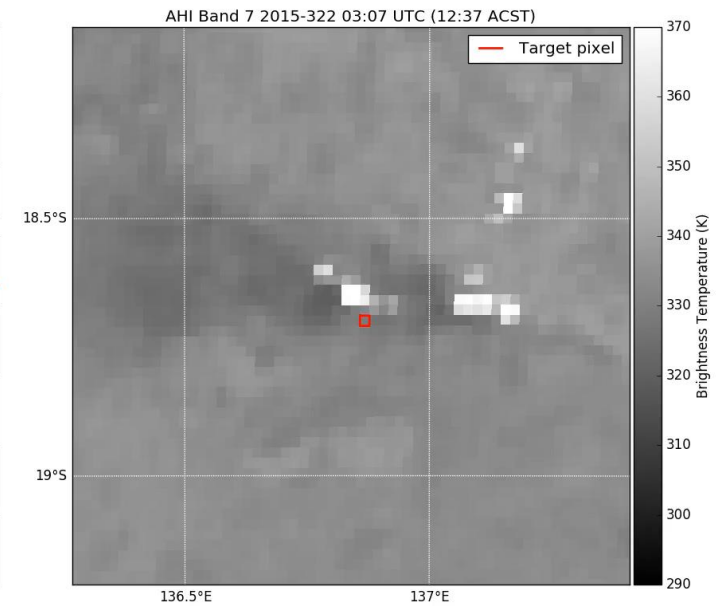
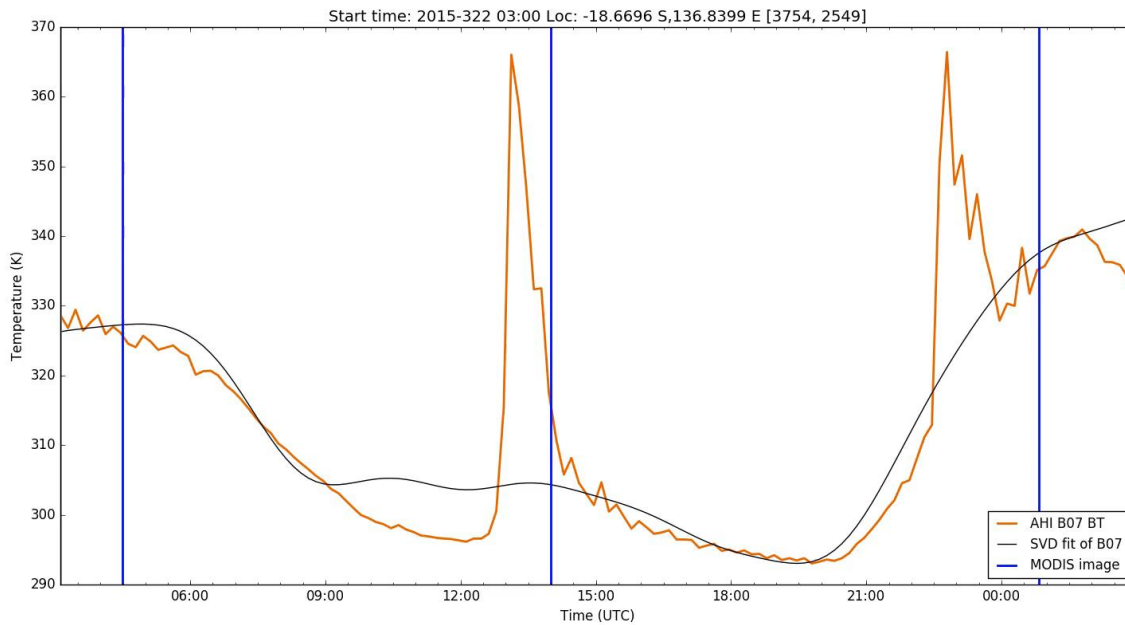
Problem	Opportunities	Solution	Benefits	End-User Community
<p><u>Consistent monitoring and timely detection of fire</u> across the Australian continent.</p> <p>Polar orbiting satellites have <u>low re-visit frequencies</u> = much of the continent is unobserved for most of the time.</p> <p>Fire detection algorithms use spatial windows to identify hotspots = <u>mixed pixels, cloud contamination</u> can lead to detection error.</p>	<p>Himawari-8 provides 10 minute observations across the entire Australian continent.</p>	<p>New paradigms to fire detection algorithms by using:</p> <ol style="list-style-type: none"> <li>geographically and seasonally varying thresholds</li> <li>tracking individual pixels against expected brightness values</li> <li>utilizing the red channel to improve resolution.</li> </ol> <p>(note: 1 of 3 solutions developed in the project)</p>	<p>Faster and improved detection accuracy.</p> <p>Scaleable processing for NRT reporting.</p> <p>Relieve resources for remote area monitoring.</p>	<p>Emergency services.</p> <p>Geoscience Australia.</p> <p>Bureau of Meteorology.</p> <p>The Community.</p>
<p><b>Research Outputs</b></p> <p>10 peer-reviewed journal publications, 2 new publications in review.</p> <p>2 PhD students, 1 Masters student.</p>			<p><b>Utilisation Activities</b></p> <p>Planning near-real time trials.</p> <p>Validation and inter-comparison.</p>	
<p><b>What has been achieved?</b></p> <p>Three independent algorithms for fire surveillance developed. Inter-comparison with MODIS, VIIRS and WF-ABB/AHI hotspots for all algorithms.</p>			<p><b>What next?</b></p> <p>Utilisation trial and review commencing Feb 2019 with the NSW Rural Fire Service and supported by the Bureau of Meteorology.</p>	





# Fire Surveillance

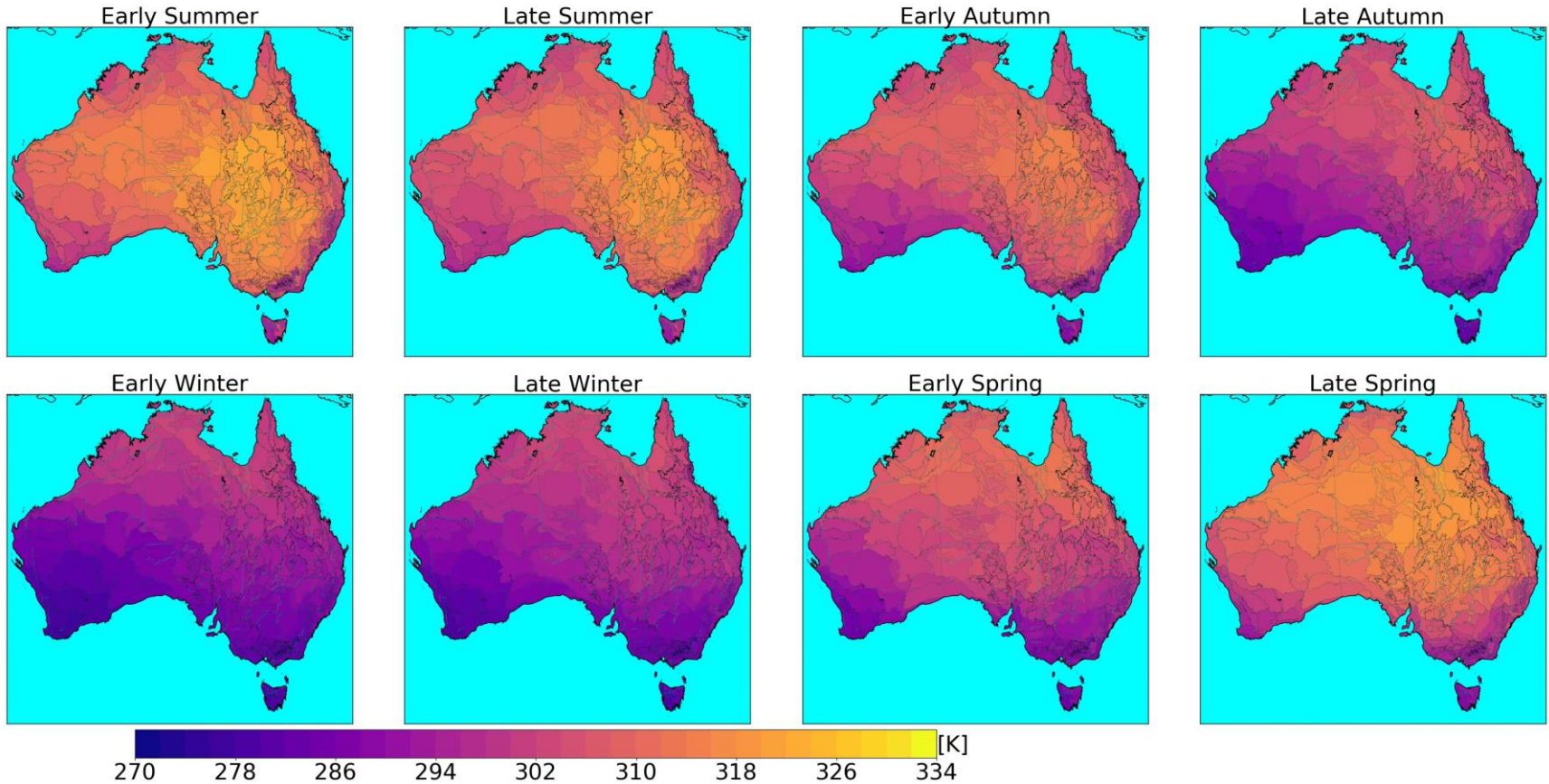
Understanding the problem



# Fire Surveillance

Understanding the problem

clear-sky MIR distribution 50th percentile for each IBRA sub-region and sub-season





# Fire Surveillance

Providing a solution

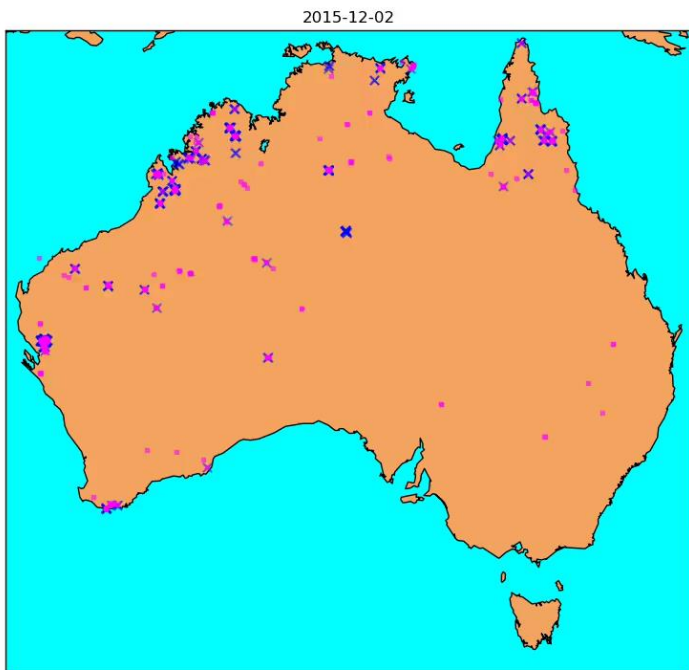
Himawari-8 image NRT acquisition

Multi-band  
2 week rolling  
window training  
data

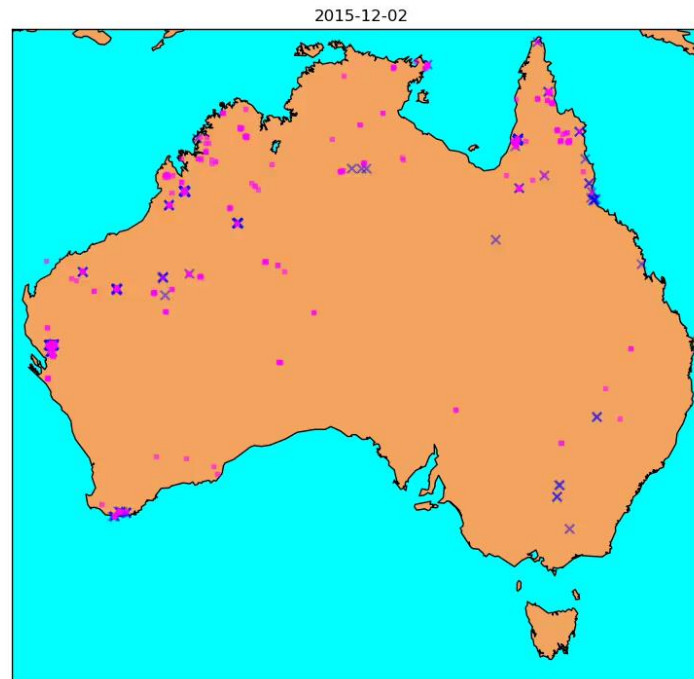
Statistically  
determined clear-  
sky observations

Statistical  
thresholding for  
fire activity

Hotspot products



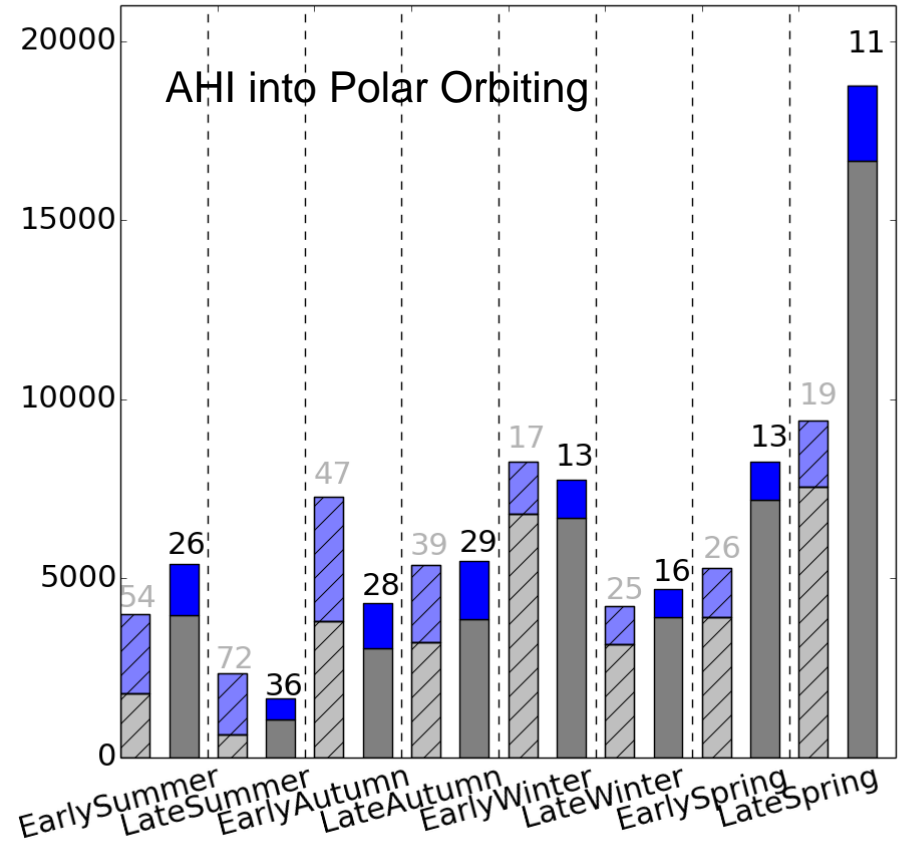
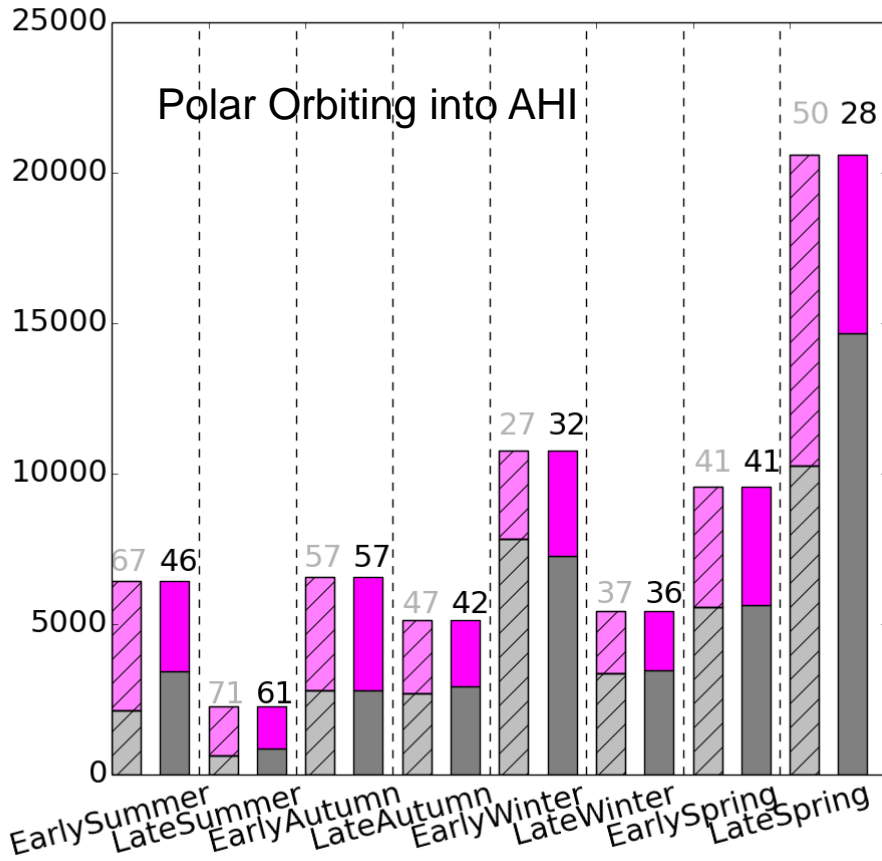
New AHI algorithm for Australia




WF-ABBA for Australia

# Fire Surveillance

Evaluating the solution



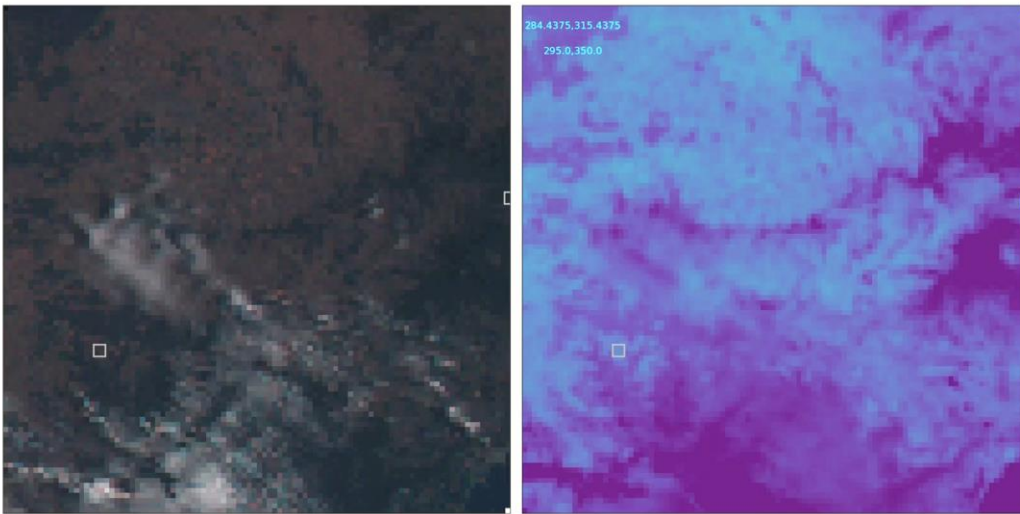
 AHI/WFABBA


 AHI/IBRA




# Fire Surveillance

Where to next?



 strong

 moderate

 low

- Comparison of first detection times from AHI-IBRA hotspot detections versus trip zero incident reports. (When and where do these occur?)
- Tweaking and continual improvement of the algorithm?
- Stretching algorithms to new applications.
- Detection strength or hotspot confidence intervals.



# End-User Perspective

Dr. Stuart Matthews  
New South Wales, Rural Fire Service

